

Air Entrainment by Viscous Contact Lines

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The entrainment of air by advancing contact lines is studied by plunging a solid plate into a very viscous liquid. Above a threshold velocity, we observe the formation of an extended air film, typically 10 microns thick, which subsequently decays into air bubbles. Exploring a large range of viscous liquids, we find an unexpectedly weak dependence of entrainment speed on liquid viscosity, pointing towards a crucial role of the flow inside the air film. This induces a striking asymmetry between wetting and dewetting: while the breakup of the air film strongly resembles the dewetting of a liquid film, the wetting speeds are larger by orders of magnitude.

Objects that impact on a liquid interface can entrain small bubbles of air into the liquid. This happens for example when raindrops fall in the ocean [1] or when liquid is poured into a reservoir at sufficiently large speeds [2, 3]. Such entrainment of air is often a limiting factor in industrial applications such as coating and nano-scale printing techniques, where the bubbles disturb the process [4, 5]. A well studied case is the entrainment of air by very viscous jets impacting on a reservoir of the same liquid [2, 3, 6, 7]. The onset of entrainment is essentially determined by the properties of the liquid, $U_e \sim \gamma/\eta_\ell$, which reflects a balance of the liquid viscosity η_ℓ and the surface tension γ . Changing the nature of the gas only has a minor influence on the entrainment process [2, 3].

A very different picture has emerged recently in the context of drops impacting on a wall, for which the presence of air has a dramatic effect [8]. It was found that splashing can be suppressed completely by reducing the air pressure to about a third of the atmospheric pressure. This caused huge excitement [9–13], in particular because such a pressure reduction does not lead to any change of the gas viscosity η_g : pressure only affects the gas density, and thus the speed of sound and the mean free path in the gas. A similar paradox is encountered for air entrainment by rapidly advancing contact lines, where a liquid advances over a surface that it partially wets [4, 14–18]. Once again, it was found that depressurizing the gas leads to a significant increase of the threshold of air entrainment [18, 19]. This contradicts the classical viewpoint that, for given wettability, the contact line speed depends mainly on the liquid properties as $\sim \gamma/\eta_\ell$ [14, 20–22], with minor influence of the gaseous phase.

In this Letter we reveal the role of the air for advancing contact lines in a paradigmatic system: a partially wetting solid plate is plunged into a reservoir of viscous liquid (Fig. 1). At sufficiently high speeds we observe the entrainment of an air film, typically 10 microns thick, which subsequently decays into bubbles. The liquid viscosity η_ℓ is varied over more than two decades by using silicon oils of different molecular weights. It is found

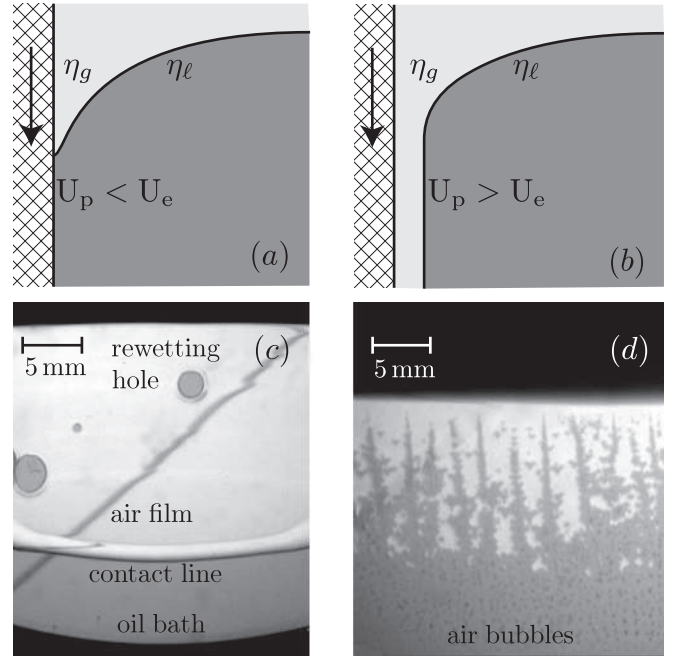


FIG. 1: Air entrainment by a contact line when a solid plate is plunged into a viscous liquid. (a,b) Sketch of dynamical meniscus below the threshold of air entrainment (a), and above the threshold of air entrainment (b). In the latter case a film of thickness h is formed. (c,d) Experimental images of the entrained air film in silicone oils of varying viscosity η_ℓ . (c) For $\eta_\ell = 0.1$ Pa.s, an extended air film is entrained behind the contact line moving downwards into the bath. The film is destroyed by the formation of “rewetting” holes. The diagonal dark line is the reflection of a straight wire that gives an impression of the interface profile. (d) For a more viscous oil, $\eta_\ell = 5$ Pa.s, the entrained air film is rapidly destabilized to form small bubbles (dark spots).

that the entrainment speed U_e changes much less than the expected scaling $\sim 1/\eta_\ell$. Using an approximate hydrodynamic model we argue that this can be attributed to the flow of air into the strongly confined film, making the contact line velocity strongly dependent on both gas and liquid viscosities. This induces a striking asym-

metry between wetting and dewetting: the same liquid can advance much faster than it recedes, by orders of magnitude.

The experiments are carried out using silicon oils (PDMS, Rhodorsil 47V series) with dynamic viscosities $\eta_\ell = 0.02, 0.10, 0.5, 1.0$ and 5 Pa.s. These liquids are essentially non-volatile, insensitive to contamination, while the surface tension $\gamma = 22$ mN.m $^{-1}$ and density $\rho = 980$ kg.m $^{-3}$ are approximately constant for all viscosities. The reservoir is a transparent acrylic container of size 29x15x13.5 cm, which is much larger than the capillary length $\ell_\gamma = (\gamma/\rho g)^{1/2} = 1.5$ mm. The substrate consists of a silicon wafer (circular, diameter 10 cm), which is coated by a thin layer of fluorinated material (FC 725 (3M) in ethyl acetate). For all liquids, this results into static contact angles between 51° and 57° . The wafer is clamped onto a 10 mm thick metallic blade screwed to a 50 cm long high-speed linear stage. The combination of controlled speeds and very viscous liquids one avoids complexities of splashing as well as the formation of interface cusps [4, 14, 16–18]. In addition the effect of inertia is eliminated both in the gas and in the liquid; the relevant Reynolds numbers are at worst ~ 1 , but typically orders of magnitude smaller. For each liquid, we plunge the wafer into the reservoir at different plate velocities U_p , up to 0.7 m/s. The process is recorded using a high-speed Photron SA3 camera (2000 Hz, 1024x1024 pixels). The plate and contact line velocities are then extracted from space-time diagrams using a correlation technique with a sub-pixel resolution, leading to a precision within a percent. Reproducibility is within 15%. The film thickness h is determined from an accurate measurement of the volume of air entrained in the bath. The air bubbles trapped at the end of an experiment are imaged with Nikon D300s (4288x2848 pixels) mounted with macro-lens. The size of each bubble is determined within a $10\text{ }\mu\text{m}$ resolution, by fitting an elliptic shape. Most of the uncertainty on h results from the estimate of the surface covered by the air film.

The experimental scenario is presented in Fig. 1. At small speeds we observe that the contact line equilibrates to form a stationary meniscus and no air is entrained into the liquid (Fig. 1a). Above a critical velocity, however, the contact line keeps moving downward into the reservoir and deposits a thin film of air (Fig. 1b). Subsequently, the air film breaks up into small air bubbles. The dynamical structures that appear during the breakup of the film turn out to depend strongly on the oil viscosity, as can be seen from the experimental images of Fig. 1cd. For the most viscous liquids the air films are very fragile and rapidly break up into smaller bubbles (Fig. 1d). However, for the lower viscosities one observes the formation of very extended air films (Fig. 1c). At the front of the film, the contact line develops a ridge-like structure that is common for dewetting of liquid films [23–25]. The peculiarity of the present experiment is that in this case

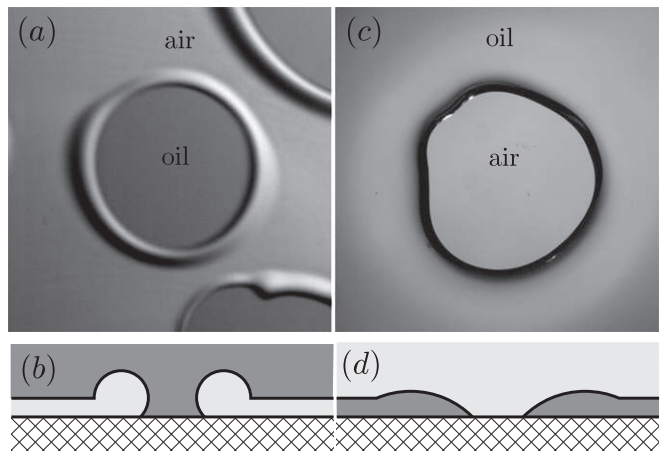


FIG. 2: “Rewetting” holes (air film invaded by liquid) as the inverse of the classical dewetting of a liquid film. (a,b) Rewetting: once the silicon oil reestablishes contact with the solid, one observes the growth of a circular zone that invades the air film. The moving front collects the air in a thick rim that is clearly visible in the image. Typical contact line speeds range from 1 to 10 cm/s for the silicone oils used in this study. (c,d) Dewetting: a thin film of silicon oil dewets in the form a circular hole. Note that for the same liquids as in (a) the typical dewetting speeds are smaller by orders of magnitude (from $40\text{ }\mu\text{m/s}$ to 1 cm/s).

the *air* is dewetted, not the liquid.

An even more striking analogy with classical dewetting of liquids is the nucleation of nearly circular regions inside the film (Fig. 1c). However, the circles now represent regions of *rewetting*, where the liquid reestablishes the contact with the solid. These “rewetting holes” can be considered as the inverse of the “dewetting holes”, since the roles of air and liquid are exchanged. Figure 2a shows a close-up of a rewetting hole (cross-section sketched in Fig. 2b). The radius of the holes increases linearly with time, and the advancing contact lines collects the air inside a thick rim. While this is analogous to the inverse problem of the dewetting holes (Fig. 2cd), the process is by no means symmetric: the rewetting holes grow with a velocity U_e that is orders of magnitude faster than their dewetting counterparts, up to a factor 1000 for the liquids used in this study.

We further quantify the velocity of air entrainment for different liquid viscosities. A first measurement of U_e is obtained from the growth velocities of the rewetting holes as in Fig. 2. A second entrainment velocity can be extracted by selecting a central part of the front of the air film, for which we obtain the contact line velocity U_{cl} in the frame of the liquid reservoir. Figure 3a reports the measured values for $\eta_\ell = 0.1$ Pa.s, showing that the contact line velocity increases linearly with plate velocity U_p . Interestingly, however, the relative velocity, $U_p - U_{cl}$, turns out to be independent of the plate velocity and therefore seems to be an intrinsic property of

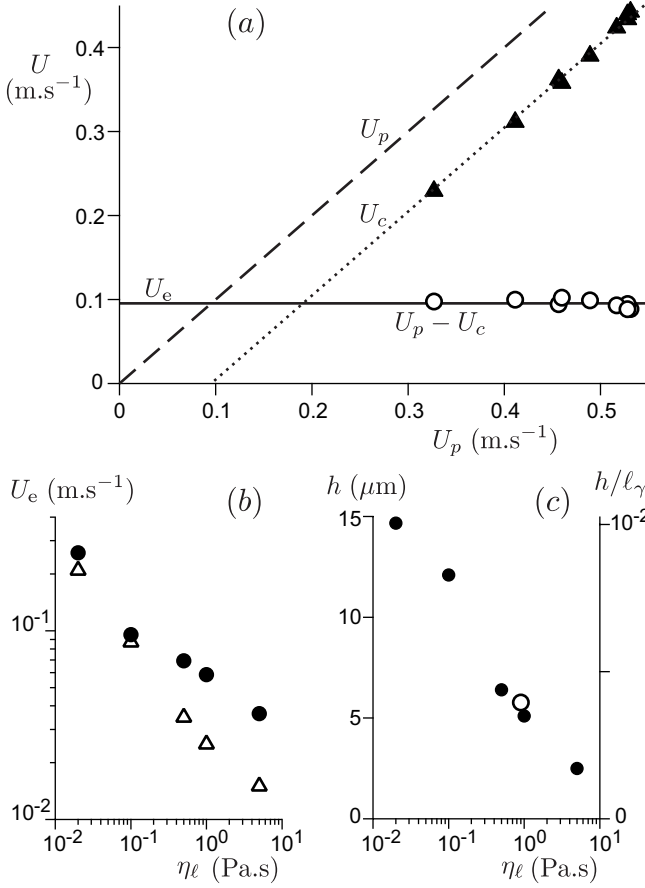


FIG. 3: (a) Contact line velocity U_c (triangles) as a function of the plate velocity U_p , for $\eta_l = 0.1 \text{ Pa.s}$. The relative velocity $U_p - U_c$ (circles) is independent of the plate speed. (b) Entrainment speed U_e for different liquid viscosities η_l , measured in two ways: the circles represent the relative velocity with respect to the plate, $U_p - U_{cl}$, while the triangles are the rewetting speeds of the holes as in Fig. 2. (c) Film thickness h for different η_l , taken at constant plate velocity $U_p = 0.67 \text{ m.s}^{-1}$. The open circle was taken for a liquid jet of glycerol entraining air at the same speed [3].

the advancing contact line. This is why we may consider the growth velocity of the rewetting holes to be an independent measurement of the entrainment velocity. The resulting entrainment velocities U_e are shown in Fig. 3b, as a function of liquid viscosity η_l . Indeed, the two experimental definitions of U_e agree very well for the smallest η_l (closed circles are based on the front of the film, open triangles correspond to rewetting holes). For larger η_l , the film rapidly destabilizes and it is more difficult to define the front of the film. This induces a difference between the two types of velocity measurements of about a factor 2; the hole velocities are certainly more reproducible in this very viscous regime.

The key result of the velocity measurements is that, although U_e decreases with liquid viscosity, the dependence is clearly much weaker than the expected $\sim 1/\eta_l$. The entrainment speed is reduced by a factor 10, while vis-

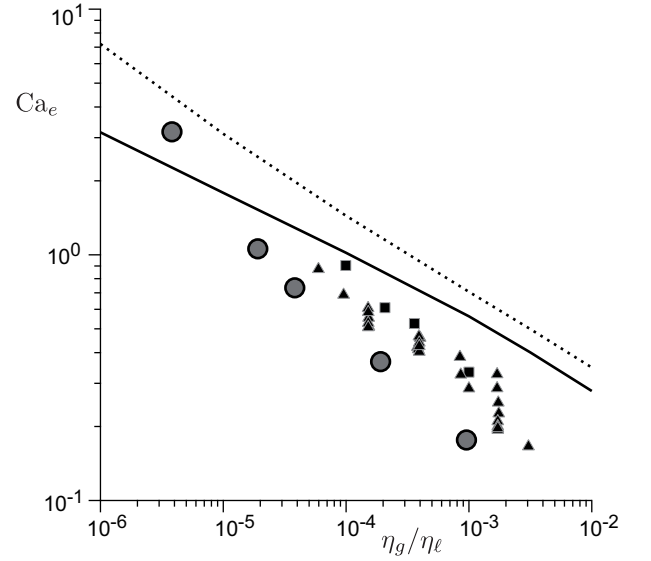


FIG. 4: Dimensionless entrainment speed, $Ca_e = U_e \eta_l / \gamma$, versus the viscosity ratio η_g / η_l for: silicon-oil/air (●), silicon-oil/air (■ after [18]) and various liquids/air (▲ after [26]). Curves: numerical results discussed in the Supplementary Material [27]. Corresponding parameters: oil slip lengths $\lambda_l = 10^{-5} \lambda_\gamma$, and air slip lengths $\lambda_g = 10^{-4} \lambda_\gamma$ (solid line) and $10^{-2} \lambda_\gamma$ (dotted line), corresponding to mean free paths $\ell_{mfp} = 70 \text{ nm}$ (solid) and $7 \mu\text{m}$ (dotted).

cosity is varied by a factor 250 (Fig. 3b). Since the liquid inertia is negligible for these highly viscous liquids, this means that the properties of the air must have a significant influence on the entrainment speed. On the other hand, the speed is not determined by the air alone, since that would yield no dependence on η_l at all. To reveal the interplay between air and liquid phases, we introduce a dimensionless capillary number, $Ca_e = U_e \eta_l / \gamma$, that is based on the liquid viscosity. The experimental results are represented in Fig. 4, showing Ca_e versus the ratio of gas and liquid viscosities η_g / η_l (closed circles). Clearly, the capillary number for air entrainment displays a dependence that is much stronger than $\sim \ln(\eta_l / \eta_g)$, which is the scaling for air entrainment by liquid jets [2, 3] and the prediction by Ref. [20]. The air thus has a much larger influence than expected. On the same figure we collected data from the coating literature, based on tapes running continuously in a bath, showing a similar trend (various symbols, see caption). Note that in these experiments the contact line typically develops a sharp cusp from which small air bubbles are emitted, rather than an extended air film.

In order to understand the influence of air, one can extend the common lubrication approximation to large slopes and 2 phase flow. In the spirit of [28, 29], we start from the analytical solutions of flow in a wedge due to Huh & Scriven [30] – see Supplementary Material for details [27]. Numerical solution of the model provides the

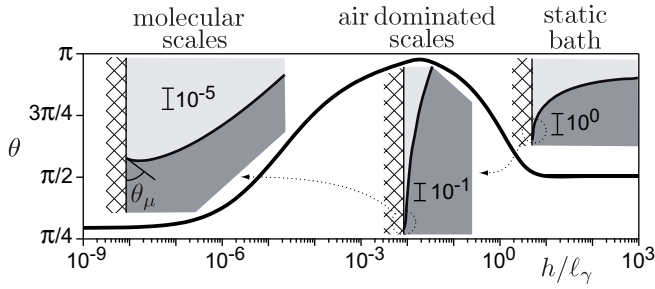


FIG. 5: Insets: shape of the dynamical meniscus at the entrainment threshold for $\eta_g/\eta_\ell = 10^{-4}$, as predicted by the hydrodynamic model [27]. Main graph: local slope θ as a function of the local thickness h . Lengths are in units of ℓ_γ .

complete profiles of the interface (Fig. 5), as well as the capillary number for entrainment. The latter is shown in Fig. 4 (solid line) and captures the order of magnitude for Ca_e as well as the unexpected, strong dependence on viscosity ratio. Since the approximation should only be valid for small interface curvature [28], the model cannot be expected to give a fully quantitative prediction. It is insightful to estimate the viscous dissipation rates, \dot{E}_g and \dot{E}_ℓ in the gas and the liquid phases. When the local contact angle θ is close to π one finds [27]:

$$\dot{E}_g \sim \frac{\eta_g U^2}{\pi - \theta}, \quad \dot{E}_\ell \sim \eta_\ell U^2 (\pi - \theta)^2, \quad (1)$$

which is different from the estimate given in [14]. Clearly, the dissipation in the gas can dominate over liquid dissipation for contact angles very close to π , with a cross-over occurring when $\eta_g/\eta_\ell \sim (\pi - \theta)^3$. As shown in Fig. 5, such angles indeed appear naturally when the liquid advances rapidly, while this is not the case when the liquid recedes. This explains the marked asymmetry between wetting and dewetting: the faster advancing speed is due to the reduced dissipation near $\theta \approx \pi$.

In conclusion, we experimentally showed that the entrainment speed of advancing contact lines does not scale as γ/η_ℓ , but exhibits a much weaker variation with liquid viscosity. We explain this by the influence of the air flow when the local angle of the interface is close to π . Can such a scenario explain the observed increase of entrainment speed when depressurizing the air [18, 19]? A pressure reduction does not affect the gas viscosity, but it does increase the mean free path ℓ_{mfp} by a factor $\sim p_{\text{atm}}/p$. Since under atmospheric conditions $\ell_{\text{mfp}} \approx 70$ nm, it is pushed well into the micron range in when pressure is reduced by a factor 100. The mean free path then becomes comparable to the film thickness measured experimentally (Fig. 3c). Interpreting ℓ_{mfp} as an effective slip in the gas [27, 31], the model indeed yields an increase of Ca_e (Fig. 4, dotted line). This provides the exciting perspective that depressurized air is a Knudsen gas when entrained by advancing contact lines.

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