

Equilibrium avalanches in spin glasses

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We study the distribution of equilibrium avalanches (shocks) in Ising spin glasses which occur at zero temperature upon small changes in the magnetic field. For the infinite-range Sherrington-Kirkpatrick model we present a detailed derivation of the density $\rho(\Delta M)$ of the magnetization jumps ΔM . It is obtained by introducing a multi-component generalization of the Parisi-Duplantier equation, which allows us to compute all cumulants of the magnetization. We find that $\rho(\Delta M) \sim \Delta M^{-\tau}$ with an avalanche exponent $\tau = 1$ for the SK model, originating from the marginal stability (criticality) of the model. It holds for jumps of size $1 \ll \Delta M < N^{1/2}$ being provoked by changes of the external field by $\delta H = O(N^{-1/2})$ where N is the total number of spins. Our general formula also suggests that the density of overlap q between initial and final state in an avalanche is $\rho(q) \sim 1/(1-q)$. These results show interesting similarities with numerical simulations for the out-of-equilibrium dynamics of the SK model. For finite-range models, using droplet arguments, we obtain the prediction $\tau = (d_f + \theta)/d_m$ where d_f , d_m and θ are the fractal dimension, magnetization exponent and energy exponent of a droplet, respectively. This formula is expected to apply to other glassy disordered systems, such as the random-field model and pinned interfaces. We make suggestions for further numerical investigations, as well as experimental studies of the Barkhausen noise in spin glasses.

I. INTRODUCTION

The low-temperature response of disordered systems often proceeds in jumps and avalanches.^{1–9} These processes are beyond standard thermodynamic calculations and are therefore relatively difficult to access and describe analytically^{10–15}. In a recent article¹⁶, we succeeded in calculating the statistics of equilibrium avalanches (also called shocks) in a variety of disordered systems described by mean-field theory based on Parisi replica symmetry breaking. This encompasses in particular the canonical Sherrington Kirkpatrick (SK) model for the Ising spin glass^{17,18} and elastic manifolds in the limit of a large number of transverse dimensions. Although it has been known for a while that the equilibrium magnetization curve $M(H)$ of the SK model undergoes a sequence of small jumps as H is increased¹⁹, their statistics had not been obtained previously. The aim of the present article is to provide a detailed derivation of the distribution of avalanche sizes for the SK model. We introduce replica techniques that significantly extend the formalism developed in Ref. 20 to study velocity correlations in high-dimensional Burger's turbulence. It also generalizes previous studies of the variance of equilibrium jumps to their full distributions^{21–23}. We expect this technique to be useful in several other contexts as well. In particular, it should be helpful to describe the response of complex systems to a small change of parameters, a problem that arises in a variety of fields ranging from condensed-matter physics of complex systems, optimization problems to econophysics^{24–27}.

The main result of our calculation is that the distribution of jumps takes a scale-free form, described by a power law of the jump size. This is intimately tied to the criticality of the spin-glass phase of the models

analyzed²⁸, and we conjecture that such a criticality is a feature of a large variety of frustrated glassy systems.²⁹ The exact result obtained in the SK model finds a natural interpretation which allows for an extension to finite dimensions via droplet scaling arguments. Those relate the equilibrium-avalanche exponent to critical properties of droplet excitations.

Our results complement previous numerical simulations by Pazmandi et al.³¹ on out-of-equilibrium hysteresis at $T = 0$ in the SK model, which exhibit surprising similarities, as we will discuss. Understanding the relations between these results requires further numerical investigations of dynamic and static avalanches, both in mean-field and finite-dimensional spin glasses. Our results suggest to look for power-law distributed Barkhausen-type noise in spin and electron glass experiments, as will be discussed.

This paper is organized as follows: In Sec. II we revisit the Parisi saddle-point equations in the presence of a small varying external magnetic field. In Sec. III, we generalize the Parisi-Duplantier equations to compute the moments of the magnetizations in different fields. From that calculation we extract the distribution of equilibrium jumps in Sec. IV. In Sec. V we consider the case of finite-dimensional spin glasses, and using droplet arguments we obtain a power-law distribution of equilibrium avalanches. In Sec. VI we discuss the connection with previous numerical studies on spin and electron glasses, and propose experimental and numerical investigations.

II. MODEL AND METHOD

A. Model and aim of the calculation

We study the SK spin-glass model of energy

$$\mathcal{H} = - \sum_{i,j=1}^N J_{ij} \sigma^i \sigma^j - H_{\text{ext}} \sum_{i=1}^N \sigma^i, \quad (1)$$

where the J_{ij} are i.i.d. centered Gaussian random variables of variance J^2/N , that couple all N Ising spins, and H_{ext} is the external field.

Our aim is to follow the equilibrium state as a function of the applied field H_{ext} at low temperature $\beta^{-1} = k_B T = T \ll J$. We consider small variations of the applied field around a reference value H , $H_{\text{ext}} = H + \frac{h}{\sqrt{N}}$.

We are interested in the total magnetization in a given sample,

$$M(H_{\text{ext}}) = \sum_i \langle \sigma^i \rangle_{H_{\text{ext}}} = -\partial_{H_{\text{ext}}} F, \quad (2)$$

where $F = -k_B T \ln \text{Tr} \exp(-\beta \mathcal{H})$ is the free energy. Since upon variation of h of order one we expect jumps of the total magnetization of order \sqrt{N} we define:

$$m_h = \frac{1}{\sqrt{N}} M\left(H + \frac{h}{\sqrt{N}}\right) = -\partial_h F(h) \quad (3)$$

where from now on we denote $F(h)$ the free energy in the external field $H + \frac{h}{\sqrt{N}}$. Note that m_h is the sum of a constant part of order \sqrt{N} , $\overline{m}_0 = \frac{\overline{M(H)}}{\sqrt{N}}$, plus a fluctuating part $m_h - \overline{m}_0$ of order unity.

To characterize the statistics of these order-one jumps in m_h we need to compute the following cumulants in different *physical* fields h_i , $i = 1, \dots, p$:

$$\overline{m_{h_1} \dots m_{h_p}}^c = \partial_{h_1} \dots \partial_{h_p} S^{(p)}(h_1, h_2, \dots, h_p). \quad (4)$$

It is obtained from the cumulants of the sample-to-sample fluctuations of the free energy,

$$S^{(p)}(h_1, h_2, \dots, h_p) = (-1)^p \overline{F(h_1) \dots F(h_p)}^{J,c}, \quad (5)$$

where we denote by $\overline{\dots}^J$ the average over disorder and $\overline{\dots}^{J,c}$ its connected average.

These can be obtained from the generating function $W[\{h^a\}] \equiv W[h]$ of $a = 1, \dots, n$ replica submitted to different fields h^a ,

$$\exp(W[h]) := \overline{\exp\left[-\beta \sum_{a=1}^n F(h^a)\right]}^J. \quad (6)$$

Note that fields h^a with replica index a are denoted with *upper* index to distinguish it from the physical field h_i with lower index. Hence

$$W[h] = \sum_{q=0}^{\infty} \frac{\beta^q}{q!} \sum_{a_1, \dots, a_q} S^{(q)}(h^{a_1}, \dots, h^{a_q}) \quad (7)$$

We now derive a formula for $W[h]$ from the saddle-point equations in the large- N limit.

B. Saddle-point equations

One has:

$$\begin{aligned} e^{W[h]} &= \overline{\exp\left[\beta \sum_{i,j} \sigma_a^i J_{ij} \sigma_a^j + \beta \sum_i \left(H + \frac{h^a}{\sqrt{N}}\right) \sigma_a^i\right]}^J \\ &= \sum_{\{\sigma_a^i\}} \int \prod_{a \neq b} dQ_{ab} \prod_i \exp\left(nN \frac{\beta^2 J^2}{2}\right) \\ &\quad \times \exp\left[\sum_a \beta \left(H + \frac{h^a}{\sqrt{N}}\right) \sigma_a^i\right] \\ &\quad \times \exp\left[\beta^2 J^2 \sum_{a \neq b} \left(-\frac{N}{2} Q_{ab}^2 + Q_{ab} \sigma_a^i \sigma_b^i\right)\right]. \end{aligned} \quad (8)$$

Note that on spins σ_a^i , we put the replica-index a at the bottom, and the site index i at the top. Now we define the *local* partition sum

$$\begin{aligned} e^{A(Q,h)} &:= \sum_{\{\sigma_a\}} \exp\left[\beta^2 J^2 \sum_{a \neq b} Q_{ab} \sigma_a \sigma_b + \beta \sum_a \left(H + \frac{h^a}{\sqrt{N}}\right) \sigma_a\right], \end{aligned} \quad (9)$$

in terms of which we can write

$$\begin{aligned} e^{W[h]} &= \int \prod_{a \neq b} dQ_{ab} \exp\left[nN \frac{\beta^2 J^2}{2} - \frac{N}{2} \beta^2 J^2 \sum_{a \neq b} Q_{ab}^2 \right. \\ &\quad \left. + NA(Q, h)\right]. \end{aligned} \quad (10)$$

In the limit of $N \rightarrow \infty$ we can perform a saddle-point evaluation. For $h^a = 0$ this is the usual SK saddle-point equation in presence of a field H . In the low-temperature phase considered here, it has a set of solutions, denoted $q_{ab}^\pi = q_{\pi^{-1}(a)\pi^{-1}(b)}$. They are obtained from the standard Parisi solution q_{ab} by applying a permutation $\pi \in \mathcal{S}(n)$ of the indices. Each saddle point q_{ab} of the path integral over Q_{ab} satisfies the self-consistent equation for $a \neq b$:

$$\langle \sigma_a \sigma_b \rangle_{A(q,0)} = q_{ab}, \quad (11)$$

where $\langle \dots \rangle_A$ refers to an average with action A from Eq. (9). Since changes in the external fields are of size h^a/\sqrt{N} , they alter the solution of the saddle-point equation from $q = q_0$ to $q_h = q_0 + O(\frac{1}{\sqrt{N}})$. Hence we can compute the contribution to $W[h]$ of each saddle point in perturbation theory. For a given saddle point, each contribution to $e^{W[h]}$ is of the form $e^{V[q_h, h]}$, with

$$V[q, h] := nN \frac{\beta^2 J^2}{2} - \frac{N}{2} \beta^2 J^2 \sum_{a \neq b} q_{ab}^2 + NA[q, h]. \quad (12)$$

The saddle-point condition satisfied for any h reads

$$\partial_{q_{ab}} V[q_h, h] = 0. \quad (13)$$

Using this equation, we obtain the following expansion in replica fields h^a :

$$\begin{aligned} V[q_h, h] &= V[q, 0] + \sum_a h^a (\partial_{h^a} V)[q, 0] \\ &\quad + \frac{1}{2} \sum_{ab} h^a h^b (\partial_{h^a h^b}^2 V)[q, 0] + O(\frac{1}{\sqrt{N}}) \\ &= V[q, 0] + \beta \sum_a h^a \overline{m_0} \\ &\quad + \frac{1}{2} \sum_{ab} h^a h^b \beta^2 [\delta_{ab} + (1 - \delta_{ab}) q_{ab}] + O(\frac{1}{\sqrt{N}}) \end{aligned}$$

In the first line we used the condition (13), its total derivative w.r.t. h^a , and that $\partial_h q_h = O(\frac{1}{\sqrt{N}})$ to eliminate the cross term $\partial_q \partial_h V$; in the second line we used Eq. (11).

The final expression for $W[h]$ is obtained by performing the sum over all saddle points $q_{ab}^\pi = q_{\pi^{-1}(a)\pi^{-1}(b)}$,

$$\begin{aligned} e^{W[h] - W[0] - \beta \sum_a h^a \overline{m_0}} \\ = \sum_{\pi} e^{\frac{\beta^2}{2} \sum_a (h^a)^2 (1 - q_{aa}) + \frac{\beta^2}{2} \sum_{ab} q_{ab}^\pi h^a h^b}. \end{aligned} \quad (14)$$

The prime on the permutation sum indicates that the sum is normalized by $\sum_{\pi} 1 = 1$. For convenience, we have introduced q_{aa} to be defined later.

Let us define the “non-trivial” part $\tilde{W}[h]$ of $W[h]$ as

$$\begin{aligned} \tilde{W}[h] &:= W[h] - W[0] - \beta \sum_a h^a \overline{m_0} \\ &\quad - \frac{\beta^2}{2} \sum_a (h^a)^2 (1 - q_{aa}) \\ &= \ln \left(\sum_{\pi} e^{\frac{\beta^2}{2} \sum_{ab} q_{ab} h^{\pi(a)} h^{\pi(b)}} \right). \end{aligned} \quad (15)$$

To obtain the p -th cumulant, we need to consider $W[\{h^a\}]$ for p groups of $n_1 = \alpha_1 n, n_2 = \alpha_2 n, \dots, n_p = \alpha_p n$ replica with $\sum_{i=1}^p \alpha_i = 1$. Each group is subject to a different physical field h_i , $i = 1, \dots, p$. This field is constant within a replica group. We remind that we use superscript indices h^a to denote replicas, and subscript indices h_i to label the replica groups. The resulting $W_p[h] := W(h_1, \dots, h_p) := W[\{h^a\}]$ (and likewise for $\tilde{W}_p[h]$) has the cumulant expansion

$$W_p[h] = \sum_q \frac{\beta^q}{q!} n^q \sum_{i_1=1}^p \dots \sum_{i_q=1}^p \alpha_{i_1} \dots \alpha_{i_q} S^{(q)}(h_{i_1}, \dots, h_{i_q}). \quad (16)$$

The magnetization cumulants for $p > 1$ can then be extracted as

$$\begin{aligned} \overline{m_{h_1} \dots m_{h_p}}^{J,c} &= \partial_{h_1} \dots \partial_{h_p} S^{(p)}(h_1, \dots, h_p) \\ &= \lim_{n \rightarrow 0} \frac{1}{n^p \beta^p \prod_{i=1}^p \alpha_i} \partial_{h_1} \dots \partial_{h_p} \tilde{W}_p[h]. \end{aligned} \quad (17)$$

This works, since the terms in (16) with $q < p$ vanish after the differentiation and the ones with $q > p$ vanish in the limit $n \rightarrow 0$, leaving the desired term $q = p$.

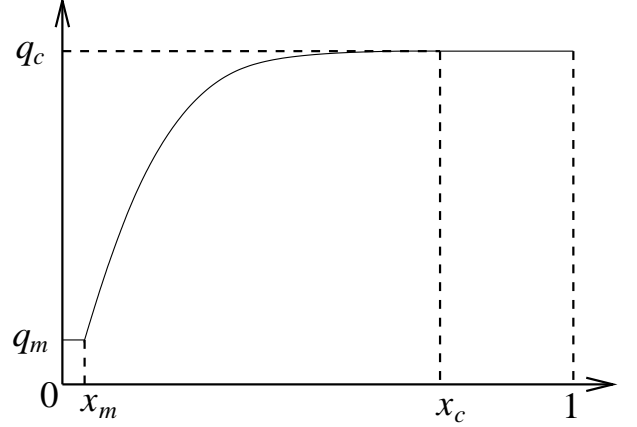


FIG. 1. The Parisi-function $q(x)$, with its two plateaus for $x < x_m$ and $x > x_c$. Note that this gives two δ -function contributions to the derivative of the inverse function, $\frac{dx(q)}{dq} = x_m \delta(q - q_m) + (1 - x_c) \delta(q - q_c) + \text{smooth part}$.

III. CALCULATION OF MOMENTS

A. Generalized flow equation

To proceed, we decouple the h_a 's by a Hubbard-Stratonovich transformation,

$$e^{\tilde{W}[h]} = \left\langle \sum_{\mu} e^{\sum_a h^{\pi(a)} \mu_a} \right\rangle_{\mu}, \quad (18)$$

where μ_a are Gaussian random variables with variance $\langle \mu_a \mu_b \rangle_{\mu} = \beta^2 q_{ab}$, and $\langle \rangle_{\mu}$ denotes the average over them.

The sum over permutations in (18) is equivalent to a normalized sum (indicated by a prime) over assignments $\{i_a\} \in \{1, \dots, p\}$, describing the permutation π :

$$h^{\pi(a)} = h_{i_a}. \quad (19)$$

Since the permutation preserves the number of equivalent replica, we have the constraint $\sum_a \delta_{j,i_a} = n \alpha_j$. With this notation we obtain

$$e^{\tilde{W}_p[h]} = \left\langle \sum_{\substack{i_a \in \{1, \dots, p\} \\ \sum_a \delta_{j,i_a} = n \alpha_j}} \exp \left(\sum_a h_{i_a} \mu_a \right) \right\rangle_{\mu}. \quad (20)$$

As we prove in App. C, this can be rewritten as

$$e^{\tilde{W}_p[h]} = \left\langle \frac{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta(\sum_{i=1}^p \alpha_i y_i) \prod_{a=1}^n [\sum_{i=1}^p \exp(h_i \mu_a + y_i)]}{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta(\sum_{i=1}^p \alpha_i y_i) [\sum_{i=1}^p \exp(y_i)]^n} \right\rangle_{\mu}, \quad (21)$$

valid for any $n < 0$, and for any set of $\alpha_i > 0$, with $\sum_{i=1}^p \alpha_i = 1$. This identity significantly generalizes the formula (D6) in Ref. 20.

In the case where q_{ab} is a hierarchical ultrametric matrix of Parisi type, parameterized by the Parisi function $q(x)$ with $n < x < 1$, the average over μ_a of expression (21) can be performed extending the methods of Ref. 43. We recall that we use everywhere $\sum_i \alpha_i = 1$ and rewrite

$$e^{\tilde{W}_p[h]} = \frac{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta(\sum_i \alpha_i y_i) g(x = n, \{y_i\})}{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta(\sum_i \alpha_i y_i) [\sum_i \exp(y_i)]^n}. \quad (22)$$

We have defined

$$g(x; \{y_i\}) \equiv e^{x\phi(x; \{y_i\})} \\ \equiv \left\langle \prod_{a=1}^x \left(\sum_{i=1}^p e^{y_i + h_i \mu_a^{(x)}} \right) \right\rangle_{\mu^{(x)}} \quad (23)$$

The auxiliary fields $\mu_a^{(x)}$ have Gaussian correlations $\langle \mu_a^{(x)} \mu_b^{(x)} \rangle_{\mu^{(x)}} = \beta^2 [q_{ab} - q(x)]$. For convenience, we define $q_{aa} = q(1)$.

Generalizing the method of Ref. 43 to several groups, we find the flow equation for the function $\phi(x, \{y_i\})$ defined above:

$$\frac{\partial \phi}{\partial x} = -\frac{\beta^2}{2} \sum_{i,j=1}^p h_i h_j \frac{dq(x)}{dx} \left(\frac{\partial^2 \phi}{\partial y_i \partial y_j} + x \frac{\partial \phi}{\partial y_i} \frac{\partial \phi}{\partial y_j} \right). \quad (24)$$

It must be solved with the boundary condition

$$\phi(x = 1; \{y_i\}) = \log \left(\sum_{i=1}^p e^{y_i} \right) \equiv H(\{y_i\}). \quad (25)$$

Here and below we denote $\vec{y} \equiv \{y_i\}$.

To simplify (22) we first evaluate the denominator. In the limit of $n \rightarrow 0$ one can show the general formula for any α_i with constraint $\sum_i \alpha_i = 1$ and $n < 0$:

$$\begin{aligned} & \int d^p y \delta\left(\sum_i \alpha_i y_i\right) e^{nH(\vec{y})} \\ &= \int d^p y \delta\left(\sum_i \alpha_i y_i\right) e^{-(n)\max(y_i)} [1 + O(n)] \\ &= \frac{1}{\prod_i \alpha_i} (-n)^{1-p} [1 + O(n)]. \end{aligned} \quad (26)$$

Expanding also the numerator and the exponential in

(22) to lowest non-trivial order in n , we find

$$\begin{aligned} & \partial_{h_1} \dots \partial_{h_p} \tilde{W}_p[h] \\ &= \frac{n \int d^p y \delta(\sum_i \alpha_i y_i) \partial_{h_1} \dots \partial_{h_p} \phi(0, \vec{y})}{(-n)^{1-p} / \prod_i \alpha_i} [1 + O(n)] \\ &= -(-n)^p \prod_{i=1}^p \alpha_i \int_{-\infty}^{\infty} d^p y \delta\left(\sum_i \alpha_i y_i\right) \partial_{h_1} \dots \partial_{h_p} \phi(0, \vec{y}) \\ &\quad \times [1 + O(n)]. \end{aligned} \quad (27)$$

Inserting this into Eq. (17) we obtain the final formula for the p -th cumulant of the reduced magnetization:

$$\begin{aligned} & \overline{m_{h_1} \dots m_{h_p}}^{J,c} \\ &= -(-T)^p \int d^p y \delta\left(\sum_i \alpha_i y_i\right) \partial_{h_1} \dots \partial_{h_p} \phi(0, \vec{y}). \end{aligned} \quad (28)$$

This expression is independent of the choice of α_i , as it must be. In case the order parameter function, $q(x)$, has a plateau for $x < x_m$ (as happens for the SK model in a magnetic field $H \neq 0$)

$$\phi(x = 0, \vec{y}) = \overline{\phi(x_m, \vec{y} + z\beta\vec{h}\sqrt{q_0})}^z, \quad (29)$$

where $\overline{\dots}^z$ denotes an average over z , a unit-centered Gaussian variable,

$$\overline{f(z)}^z := \int_{-\infty}^{\infty} \frac{dz}{\sqrt{2\pi}} e^{-z^2/2} f(z), \quad (30)$$

see Eq. (96) in Ref. 21.

B. TBL-shock expansion

We now solve the flow equation (24) perturbatively in the nonlinear term. This generates a low-temperature expansion which is well suited to study shocks²¹. We write

$$\phi(x, \vec{y}) = \phi^0(x, \vec{y}) + \phi^1(x, \vec{y}) + \dots \quad (31)$$

The successive terms satisfy

$$\frac{\partial \phi^0}{\partial x} = -\frac{\beta^2}{2} \sum_{i,j} h_i h_j \frac{q(x)}{x} \frac{\partial^2 \phi^0}{\partial y_i \partial y_j} \quad (32)$$

with initial condition $\phi^0(x = 1, \vec{y}) = H(\vec{y})$.

$$\frac{\partial \phi^1}{\partial x} = -\frac{\beta^2}{2} \sum_{i,j} h_i h_j \frac{q(x)}{x} \left(\frac{\partial^2 \phi^1}{\partial y_i \partial y_j} + x \frac{\partial \phi^0}{\partial y_i} \frac{\partial \phi^0}{\partial y_j} \right), \quad (33)$$

with initial condition $\phi^1(x = 1, \vec{y}) = 0$.

The leading-order equation (32) is a linear diffusion equation, and integrated as (for $x \geq x_m$)

$$\phi^0(x, \vec{y}) = \overline{H(\vec{y} + z\beta\vec{h}\sqrt{q(1) - q(x)})^z} \quad (34)$$

Taking into account (30), we find the contribution of ϕ^0 to the magnetization cumulants

$$\begin{aligned} \overline{m_{h_1} \dots m_{h_p}}^{J,c,(0)} &= -(-T)^p \int d^p y \delta\left(\sum_i \alpha_i y_i\right) \\ &\quad \times \partial_{h_1} \dots \partial_{h_p} \overline{H(\vec{y} + z\beta\vec{h}\sqrt{q(1)})^z} \end{aligned} \quad (35)$$

It is shown in appendix A that at $T = 0$ this equals

$$\begin{aligned} \overline{m_{h_1} \dots m_{h_p}}^{J,c,(0)} &= q(1)^{p/2} \overline{z^p} = [2q(1)]^{p/2} \frac{[(-1)^p + 1] \Gamma\left(\frac{p+1}{2}\right)}{2\sqrt{\pi}}, \end{aligned} \quad (36)$$

which is a constant independent of h_i . In addition $q(1) \rightarrow 1$ as $T \rightarrow 0$. For $p = 2$ one finds at any temperature the

contribution

$$\overline{m_{h_1}^2}^{J,c,(0)} = q(1). \quad (37)$$

Even though at $T = 0$ this is the full result for the sample-to-sample fluctuations of the magnetization, at finite T there will be an additional piece from ϕ^1 obtained below. Similarly, to obtain the full finite- T expression of higher-order moments of m_{h_1} , contributions from $\phi^{p>0}$ are needed. However, here we focus on $T = 0$.

We now turn to the calculation of the contributions which capture the information about jumps, which are of order $\mathcal{O}(|h_i - h_j|)$ in the limit $T \rightarrow 0$. It is contained in the contribution of ϕ^1 and only in that contribution, as was discussed in Ref. 21. Higher-order functions ϕ^p contain contributions of order $\mathcal{O}(|h_i - h_j|^p)$ at $T = 0$, encoding information of multi-shock correlations. To first order in the non-linear term we find, extending the calculation in Ref. 21:

$$\begin{aligned} \phi^1(x, \vec{y}) &= \int_x^1 dx' \frac{\beta^2}{2} \sum_{ij} \frac{q(x')}{x'} x' h_i h_j \overline{\frac{\partial \phi^0}{\partial y_i} \left(x', \vec{y} + \eta \beta \vec{h} D_{x'x}\right) \frac{\partial \phi^0}{\partial y_j} \left(x', \vec{y} + \eta \beta \vec{h} D_{x'x}\right)}^\eta \\ &= \int_x^1 dx' \frac{\beta^2}{2} \sum_{ij} \frac{q(x')}{x'} x' h_i h_j \overline{\frac{\partial H}{\partial y_i} \left(\vec{y} + \beta \vec{h} [\eta D_{x'x} + z_1 D_{1x'}]\right) \frac{\partial H}{\partial y_j} \left(\vec{y} + \beta \vec{h} [\eta D_{x'x} + z_2 D_{1x'}]\right)}^{\eta, z_1, z_2}. \end{aligned} \quad (38)$$

As in Eq. (30), η , z_1 and z_2 are independent unit-centered Gaussian random variables, and $D_{x'x} := \sqrt{q(x') - q(x)}$.

We now change integration variables from $x \rightarrow q$ and define $\hat{x}(q) := x(q)/T$ and $\hat{h} := h/T$, the “thermal

boundary layer variable”²¹ for the external field. Using Eq. (28) the contribution of the first-order term to the magnetization cumulant becomes, denoting $q_c := q(x_c)$, and $q_m := q(0)$, see Fig. 1,

$$\begin{aligned} \overline{m_{h_1} \dots m_{h_p}}^{J,c,(1)} &= (-1)^{p+1} \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \frac{T}{2} \int_{q_m}^{q_c} dq \hat{x}(q) \int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta\left(\sum_i \alpha_i y_i\right) \overline{\partial_{A_+} \partial_{A_-} H(\vec{y} + \vec{h} A_+) H(\vec{y} + \vec{h} A_-)}^{A_+, A_-} \\ &= (-1)^p \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \frac{T}{2} \int_{q_m}^{q_c} dq \hat{x}(q) \int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta\left(\sum_i \alpha_i y_i\right) \overline{\partial_{A_+} \partial_{A_-} \frac{1}{2} [H(\vec{y} + \vec{h} A_+) - H(\vec{y} + \vec{h} A_-)]^2}^{A_+, A_-}. \end{aligned} \quad (39)$$

A_{\pm} are centered Gaussian random variables with correlations defined from the above independent Gaussian variables as

$$A_+ = \eta \sqrt{q - q_m} + z_1 \sqrt{q_c - q} \quad (40)$$

$$A_- = \eta \sqrt{q - q_m} + z_2 \sqrt{q_c - q}. \quad (41)$$

It is convenient to introduce

$$F := A_+ + A_- , \quad G := A_+ - A_- \quad (42)$$

in terms of which one can integrate by part

$$\begin{aligned} \overline{m_{h_1} \dots m_{h_p}}^{J,c,(1)} &= (-1)^p \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \frac{T}{2} \int_{q_m}^{q_c} dq \hat{x}(q) \int_{-\infty}^{\infty} dF \int_{-\infty}^{\infty} dG (\partial_F^2 - \partial_G^2) \frac{\exp\left(-\frac{F^2}{4[q_c+q-2q_m]} - \frac{G^2}{4[q_c-q]}\right)}{2\pi\sqrt{2[q_c+q-2q_m]2(q_c-q)}} \\ &\quad \times \prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta\left(\sum_i \alpha_i y_i\right) \frac{1}{2} \left[H\left(\vec{y} + \frac{1}{2}\vec{h}(F+G)\right) - H\left(\vec{y} + \frac{1}{2}\vec{h}(F-G)\right) \right]^2. \end{aligned} \quad (43)$$

The differential operator $\partial_{A_+} \partial_{A_-} = \partial_F^2 - \partial_G^2$ acts only on the Gaussian measure. Note that its action is equivalent to $\partial_F^2 - \partial_G^2 \equiv d/dq$. One can thus integrate by part over q to get

$$\begin{aligned} \overline{m_{h_1} \dots m_{h_p}}^{J,c,(1)} &= \frac{(-1)^{p+1}T}{4} \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \int_{q_m}^{q_c} dq \frac{d\hat{x}(q)}{dq} \\ &\quad \times \prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta\left(\sum_i \alpha_i y_i\right) \overline{\left[H\left(\vec{y} + \frac{1}{2}\vec{h}(F+G)\right) - H\left(\vec{y} + \frac{1}{2}\vec{h}(F-G)\right) \right]^2}^{F,G}. \end{aligned} \quad (44)$$

The measure over F and G is defined by

$$\overline{f(F,G)}^{F,G} := \int_{-\infty}^{\infty} dF \int_{-\infty}^{\infty} dG \frac{\exp\left(-\frac{F^2}{4[q_c+q-2q_m]} - \frac{G^2}{4[q_c-q]}\right)}{2\pi\sqrt{2[q_c+q-2q_m]2(q_c-q)}} f(F,G). \quad (45)$$

Equivalently, one can write in terms of A_+ and A_-

$$\overline{m_{h_1} \dots m_{h_p}}^{J,c,(1)} = \frac{(-1)^{p+1}T}{4} \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \int_{q_m}^{q_c} dq \frac{d\hat{x}(q)}{dq} \prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta\left(\sum_i \alpha_i y_i\right) \overline{\left[H\left(\vec{y} + \vec{h}A_+\right) - H\left(\vec{y} + \vec{h}A_-\right) \right]^2}^{A_+,A_-} \quad (46)$$

with measure

$$\overline{f(A_+,A_-)}^{A_+,A_-} := \int_{-\infty}^{\infty} dA_+ \int_{-\infty}^{\infty} dA_- \frac{\exp\left(-\frac{(A_++A_-)^2}{4[q_c+q-2q_m]} - \frac{(A_+-A_-)^2}{4[q_c-q]}\right)}{\pi\sqrt{2[q_c+q-2q_m]2(q_c-q)}} f(A_+,A_-). \quad (47)$$

The boundary terms in the integration by part vanish, provided that whenever $q(x)$ exhibits a plateau for $0 \leq x \leq x_m$ it is included as a δ function.

Using the expression (25) for $H(y)$, the formula (44) allows us to compute the thermal boundary-layer form of the p -th cumulant. We give here the result for $p = 2$:

$$\begin{aligned} \overline{m_{h_1} m_{h_2}}^{J,c,(1)} &= -\frac{1}{4} \int_{q_m}^{q_c} dq \frac{d\hat{x}(q)}{dq} \int_{-\infty}^{\infty} dG \left[\frac{\exp\left(-\frac{G^2}{4[q_c-q]}\right)}{\sqrt{4\pi[q_c-q]}} \right] \\ &\quad \times G^3 (h_1 - h_2) \coth\left(\frac{(h_1 - h_2)G}{2T}\right), \end{aligned} \quad (48)$$

recovering the form obtained in Ref²¹. For $T > 0$ and $h_2 \rightarrow h_1$ one finds

$$\overline{m_{h_1} m_{h_1}}^{J,c,(1)} = \int_0^1 q(x) dx - q(1). \quad (49)$$

Added to Eq. (37), this gives the correct total sample-to-sample fluctuations of the magnetization. The fact that higher terms ϕ^p do not contribute to this variance can be verified by a direct expansion of Eq. (24) in $q(x)$.

For general p we only study the limit $T \rightarrow 0$. For convenience we introduce the notation $A_M \equiv \max(A_+, A_-) = (F + |G|)/2$, $A_m \equiv \min(A_+, A_-) = (F - |G|)/2$. The calculation is performed in Appendix B and we obtain for $p \geq 2$:

$$\overline{m_{h_1} \dots m_{h_p}}^{J,c,(1)} = \frac{1}{2} \int_{q_m}^{q_c} dq \frac{d\hat{x}(q)}{dq} (A_M - A_m) \overline{\left(-h_p A_m^p + \sum_{m=1}^{p-1} (h_{p-m+1} - h_{p-m}) A_m^{p-m} A_M^m + h_1 A_M^p \right)}^{A_+,A_-}. \quad (50)$$

Note that we have put back the physical field $h = T\hat{h}$, making evident the result in the limit of $T \rightarrow 0$.

As an example, for $p = 2$ we obtain

$$\overline{m_{h_1} m_{h_2}}^{J,c,(1)} = -\frac{1}{4} \int_{q_m}^{q_c} dq |h_1 - h_2| \frac{d\hat{x}(q)}{dq} \overline{|G|^3}^G \quad (51)$$

which is the $T = 0$ limit of (48). Note that this describes

the correction to order $|h_2 - h_1|$ to the 2-point function of the magnetization (37). This encodes the second moment of the jump-size distribution, as was discussed in Ref. 21 for the random-manifold problem. We now turn to the determination of the full distribution from the above cumulants.

C. Distribution of jumps

We now derive the distribution of jumps by showing that the above result is identical to a p -point correlator of the magnetization of a two-level system, whose characteristics (jump size and jump location) are distributed in a simple manner. We notice that the above expression (50) for the cumulants can be reexpressed as

$$\begin{aligned} & \overline{m_{h_1} \dots m_{h_p}}^{J,c,(1)} \\ &= \frac{1}{2} \int_{q_m}^{q_c} dq \frac{d\hat{x}(q)}{dq} \\ & \times \overline{|G| \langle \mu(h_1) \dots \mu(h_p) - \mu(0) \dots \mu(0) \rangle}_{h_c}^{F,G} \end{aligned} \quad (52)$$

in terms of the “random magnetization” variable

$$\begin{aligned} \mu(h) &= \theta(h - h_c) A_M + \theta(h_c - h) A_m \\ &= \frac{F}{2} + \text{sign}(h - h_c) \frac{|G|}{2}. \end{aligned} \quad (53)$$

It exhibits a jump of size $|G|$ at location $h = h_c$, uniformly distributed on the real axis with unit density. $F/2$ is interpreted as the mean magnetization. To prove this,

we have to show that

$$\begin{aligned} & -h_p A_m^p + \sum_{m=1}^{p-1} (h_{p-m+1} - h_{p-m}) A_m^{p-m} A_M^m + h_1 A_M^p \\ &= \langle \mu(h_1) \dots \mu(h_p) - \mu(0) \dots \mu(0) \rangle_{h_c}, \end{aligned} \quad (54)$$

where the overbar denotes averaging with respect to h_c . To see that, consider an interval $[h_0, h_L]$ containing 0 and $h_0 < 0 < h_1 < \dots < h_p < h_L$, in which h_c is uniformly distributed with density $\rho_0 = 1$.

The probability of h_c to be in the interval $[h_{p-m+1}, h_{p-m}]$ is $\rho_0(h_{p-m+1} - h_{p-m})$. Then $\overline{\mu(h_1) \dots \mu(h_p)}^{h_c}$ gives the corresponding term in the sum (54) (multiplied by ρ_0). At the edge, when $h_c < h_1$, it gives $\rho_0(h_1 - h_0) A_M^p$. When $h_c > h_p$ it gives $\rho_0(h_L - h_p) A_M^p$. Subtracting $\overline{\mu(0) \dots \mu(0)} = \rho_0 h_L A_M^p - \rho_0 h_0 A_M^p$ yields (54), (multiplied by ρ_0 , which is set to unity). Both mean magnetization $F/2$ and jump-size $|G|$ are obtained from Gaussian variables with a q -dependent variance. The full result in (52) is obtained by weighting with the probability distribution of the various values of q .

A given shock at field $h = h_s$ is characterized by its magnetization jump of size $\Delta m = m_{h+} - m_{h-}$ (always > 0), and its mean magnetization $m_s = \frac{1}{2} \left[M(H + \frac{h}{\sqrt{N}}) + M(H) \right]$ at the shock. From the above we can extract the joint density (per unit interval of h), $\rho(\Delta m, \delta m)$, of shocks of size Δm , and shift $\delta m = m_s - \bar{m}_0$. It is defined as:

$$\rho(\Delta m, \delta m) = \lim_{h \downarrow 0} \frac{1}{h} \delta \left(\Delta m - \frac{M(H + \frac{h}{\sqrt{N}}) - M(H)}{\sqrt{N}} \right) \delta \left(\delta m - \frac{M(H + \frac{h}{\sqrt{N}}) + M(H) - 2\bar{M}(H)}{2\sqrt{N}} \right), \quad (55)$$

and can be extracted from Eqs. (52) and (45), identifying δm with $F/2$, and Δm with $|G|$ as discussed above. This leads to

$$\rho(\Delta m, \delta m) = \theta(\Delta m) \Delta m \int_{q_m}^{q_c} dq \frac{d\hat{x}(q)}{dq} \frac{\exp\left(-\frac{(\delta m)^2}{[q_c + q - 2q_m]}\right)}{\sqrt{\pi[q_c + q - 2q_m]}} \frac{\exp\left(-\frac{(\Delta m)^2}{4[q_c - q]}\right)}{\sqrt{4\pi[q_c - q]}}. \quad (56)$$

Note that after integration over q , the jump size and the magnetization shift become correlated. Integrating out the magnetization shift, we obtain our main result, the density of shock sizes per unit interval of h (at $T = 0$):

$$\rho(\Delta m) = \theta(\Delta m) \Delta m \int_{q_m}^{q_c} dq \frac{d\hat{x}(q)}{dq} \frac{\exp\left(-\frac{(\Delta m)^2}{4[q_c - q]}\right)}{\sqrt{4\pi[q_c - q]}}. \quad (57)$$

This formula is valid for a large class of models described by replica symmetry breaking saddle points, as emphasized in¹⁶. Here, we will focus on its application to the SK model. Apart from the prefactor Δm , the above for-

mula is essentially a superposition of Gaussians (at fixed overlap distance q). Their contribution is weighted by the density

$$\nu(q) = \frac{d\hat{x}(q)}{dq} = \frac{1}{T} P(q). \quad (58)$$

where $P(q)$ is the sample averaged probability distribution of overlaps between metastable states sampled from the Gibbs distribution.¹⁸ The weight $\nu(q)$ can be interpreted as the probability density of finding a metastable state at overlap within $[q, q + dq]$ and energy within $[E, E + dE]$, with E close to the ground state. We will

come back to this interpretation below.

A useful check of Eq. (57) is provided by the average magnetization jump. It is

$$\begin{aligned} \int_0^\infty \rho(\Delta m) \Delta m d\Delta m &= \int_{q_m}^{q(x_c)} dq \frac{d\hat{x}(q)}{dq} [q_c - q(x)] \\ &= \lim_{T \rightarrow 0} \frac{1}{T} \int_0^1 dx [q_c - q(x)], \end{aligned} \quad (59)$$

where we remind that our definition of $\hat{x}(q)$ contains a δ -function contribution at each plateau, so that the final integral over x runs again from 0 to 1. This formula is generally valid¹⁸. For the SK model it can be rewritten in terms of the thermodynamic (field cooled) susceptibility,

$$\int_0^\infty \rho(\Delta m) \Delta m d\Delta m = \lim_{T \rightarrow 0} [\chi_{\text{FC}} - \chi_{\text{ZFC}}] = \chi_{\text{FC}}^{(T=0)},$$

since in the SK model the intra-state (zero-field cooled) susceptibility, $\chi_{\text{ZFC}} = [1 - q_c]/T$, vanishes linearly as $T \rightarrow 0$. Thus, the response is entirely due to inter-state transitions in the form of avalanches (shocks). This is in contrast to other mean-field models, where even at $T = 0$ part of the response is due to smooth intra-state polarizability¹⁶.

IV. APPLICATION TO THE SK MODEL

A. Study of the distribution of jumps: $H = 0$

In order to evaluate the distribution of jumps, we need the full replica-symmetry breaking solution of the SK model in the limit of $T \rightarrow 0$. The increasing function $q(x)$ is well characterized^{35–38}, even though no closed analytical formula is known. $q(x)$ has a continuous part up to the “break point” $x_c \approx 0.55$, and is constant for $x_c \leq x \leq 1$. In the limit of $T \rightarrow 0$ this constant q_c behaves as $1 - 1.592T^2$, and $q(x)$ becomes essentially a function of $\hat{x} = x/T$ that we call $q(\hat{x})$. In the absence of a magnetic field $H = 0$, $q_m = 0$ and $q(\hat{x}) \approx \frac{\hat{x}}{\nu(0)}$ with $\nu(0) = 1.34523$ at small \hat{x} .³⁸ At large \hat{x} the function crosses over to the asymptotic behavior $1 - q(\hat{x}) \approx 4C^2/\hat{x}^2 + BT^2$ with $C = 0.32047$ and $B = O(1)$. This leads to a power-law tail for the weight of large overlaps $q \rightarrow 1$ ³⁶,

$$\nu(q|1 \gg 1 - q \gg T^2) = C(1 - q)^{-3/2}. \quad (60)$$

We can now analyze the jump-size density using formula (57). We obtain analytical expressions in the limits of small and large Δm . Numerical calculations describing the full range are shown in Fig. 2. For small Δm the integral over q is controlled by $1 - q \ll 1$, and we can approximate

$$\begin{aligned} \rho(\Delta m) &\approx \int_{-\infty}^1 \frac{C dq}{(1 - q)^{3/2}} \Delta m \frac{\exp\left(-\frac{(\Delta m)^2}{4(1 - q)}\right)}{\sqrt{4\pi(1 - q)}} \\ &= \frac{2C}{\sqrt{\pi}} \frac{1}{(\Delta m)^\tau}, \quad \Delta m \ll 1 \end{aligned} \quad (61)$$

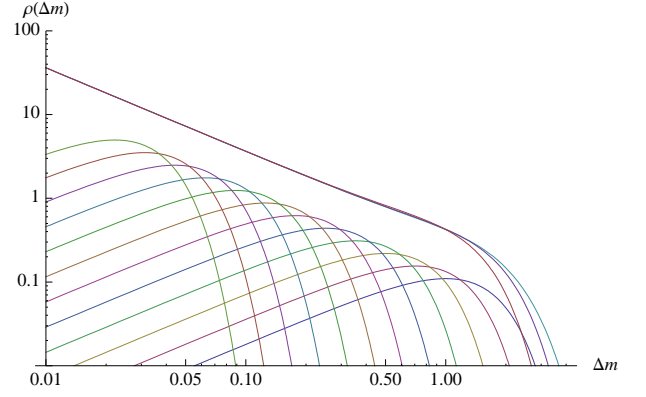


FIG. 2. Power-law density of jump sizes for the SK model. The power law receives contributions from all overlaps $1 - q$. The curves in the lower part show the contributions from $(1 - q) = 2^{-k}$, $k = 1, \dots, 12$, each of which takes the form of the jump density in mean field glasses with 1-step replica symmetry breaking. The three nearly coinciding lines on the top show $\rho(\Delta m)$ evaluated from Eq. (57), for external fields $H = 0, 0.25$ and 0.5 , respectively, using approximations for $q(\hat{x})$ described in the text. The increase of H decreases the cutoff at large Δm , while the avalanche distribution for $\Delta m \ll 1$ is a universal power law, not affected by H .

with $\tau = 1$. The universal exponent $\tau = 1$ for jump sizes $N^{-1/2} \ll \Delta m \ll 1$ results from superposed contributions from many overlaps, i.e. all scales, as illustrated in Fig. 2.

The asymptotics for large Δm is controlled by small $q \ll 1$, i.e., by transitions between very distant states. Injecting the density of states $\nu(0)$ near $q = 0$ and Taylor expanding in q inside the exponential yields the estimate

$$\begin{aligned} \rho(\Delta m) &\approx \nu(0) \Delta m \int_0^\infty dq \frac{\exp\left(-\frac{(\Delta m)^2(1+q)}{4}\right)}{\sqrt{4\pi}} \\ &= \frac{2\nu(0)}{\sqrt{\pi}} \frac{e^{-(\Delta m)^2/4}}{(\Delta m)^{\tau'}} \quad , \quad \Delta m \gg 1, \end{aligned} \quad (62)$$

with $\tau' = 1$. We see that avalanches with $\Delta m \gg 1$ ($\Delta m \gg \sqrt{N}$) are exponentially suppressed.

Plots at intermediate $\Delta m = O(1)$ are shown in Fig. 2 for three different values of the external field. As no analytical closed form for $q(\hat{x})$ is available, we have used approximations of the type $\hat{x}(q) = (aq + bq^2)/\sqrt{1 - q}$ with $a = 1.28$ and $b = -0.64$, proposed in the literature^{35,40}, and a sharp lower cutoff at³⁸ $q_{\min}(H) = 1.0H^{2/3}$.

B. Distribution of jumps: $H \neq 0$

In the presence of a finite field H , Parisi’s solution develops a plateau at low \hat{x} :

$$q(\hat{x} < \hat{x}_m) = q_m(H), \quad (63)$$

where $q_m(H) \approx 1.0H^{2/3}$ and $\hat{x}_m \approx \nu(0)q_m(H)$ for small H , while $q(\hat{x})$ is nearly unchanged for $\hat{x} > \hat{x}_m$.^{18,35,38} It

is convenient to rewrite formula (57) as

$$\rho(\Delta m) = \theta(\Delta m) \Delta m \int_{q_m(H)^-}^{q_c} dq \nu(q) \frac{\exp\left(-\frac{(\Delta m)^2}{4(q_c - q)}\right)}{\sqrt{4\pi(q_c - q)}}. \quad (64)$$

where the density of states $\nu(q)$ contains a piece $\delta(q - q_m)x_m/T$ when $q(x)$ exhibits a plateau at $x \leq x_m$, hence the notation q_m^- in the integral. Thus, the effect of a magnetic field is to change the behavior of the jump distribution at large Δm , where it is now dominated by the plateau:

$$\rho(\Delta m) = \theta(\Delta m) \Delta m \hat{x}_m \frac{\exp\left(-\frac{(\Delta m)^2}{4[1 - q_m(H)]}\right)}{\sqrt{4\pi[1 - q_m(H)]}}. \quad (65)$$

Comparing with Eq. (62) we find an effective exponent $\tau' = -1$ (instead of 1) in the tail of the distribution. The formula (65) holds only if we can neglect the contribution of the continuous part of $q(x)$. A simple comparison with the previous section shows that this holds when $\Delta m \gg \Delta m_H \sim 1/\hat{x}_m^{1/2} \sim H^{-1/3}$. For $1 \ll \Delta m \ll \Delta m_H$ the behavior crosses over to a formula similar to (62) with $\tau' = 1$.

Note that a small random field also produces a plateau in $q(x)$, and hence, we expect its effect on $\rho(\Delta m)$ to be rather similar to that of a uniform field.

C. Interpretation for the SK model

To find a natural interpretation of formula (57) we consider what happens upon increasing h from h_1 to h_2 . If we take $h_{21} = h_2 - h_1 \ll 1$ we only need to consider the possibility that the ground state and the lowest-lying metastable state cross as we tune h , corrections due to higher excited states being of order $O(h_{12}^2)$.

We now argue that the disorder-averaged density of states of this two-level system is given by $\nu(q)dq dE$, where $\nu(q)$ was defined in Eq. (58). Indeed, the definition of the overlap distribution $P(q)$ is

$$P(q) = \sum_{\alpha, \gamma} w_\alpha w_\gamma \delta(q - q_{\alpha\gamma}) \quad (66)$$

where $w_\alpha = \exp(-\beta F_\alpha) / \sum_\gamma \exp(-\beta F_\gamma)$ is the Gibbs weight of the metastable state α . At low T we can restrict to the two lowest states, which yield the leading-order term in

$$P(q) = (1 - T)\delta(q - q_c) + T\rho_1(q) + O(T^2) \quad (67)$$

as

$$\begin{aligned} T\rho_1(q) &= \int_0^\infty dE \nu(q, E) \frac{2e^{-\beta E}}{(1 + e^{-\beta E})^2} \\ &= T\nu(q, 0) + O(T^2). \end{aligned} \quad (68)$$

Here $\nu(q, E)$ is the joint probability density of overlap q and free-energy difference E between the ground and first excited state. Hence Eq. (58) holds with $\nu(q) = \nu(q, 0)$.

The two states differ in $N_{\text{fl}} = N(1 - q)/2$ flipped spins. In the SK model the magnetization is uncorrelated with the energy, and one thus expects the magnetization difference between the states to be a Gaussian variable of zero mean and variance (at fixed overlap)

$$\langle \Delta m^2 \rangle_q = 4N_{\text{fl}}/N = 2(1 - q). \quad (69)$$

When h increases the energy difference between the first excited state and the ground state changes from E (for $h = h_1$) to $E - h_{21}\Delta m$, where $h_{21} := h_2 - h_1 > 0$. Thus, if $\Delta m > 0$, a jump at equilibrium occurs when $h_{21} = E/\Delta m$. For the shock probability per unit h one thus expects

$$\begin{aligned} \rho(\Delta m) &= \lim_{h_{21} \downarrow 0} \int_{q_m^-}^{q_c} dq \int_0^\infty dE \nu(q, E) \\ &\quad \times \frac{\exp\left(-\frac{(\Delta m)^2}{2\langle \Delta m^2 \rangle_q}\right)}{\sqrt{2\pi\langle \Delta m^2 \rangle_q}} \delta\left(h_{21} - \frac{E}{\Delta m}\right), \end{aligned} \quad (70)$$

reproducing Eq. (57) upon integration over E .

This argument strongly suggests that the joint density (per unit of h) of jumps with characteristics q and Δm , is given by

$$\rho(\Delta m, q) = \theta(\Delta m) \Delta m \nu(q) \frac{\exp\left(-\frac{(\Delta m)^2}{2\langle \Delta m^2 \rangle_q}\right)}{\sqrt{2\pi\langle \Delta m^2 \rangle_q}}. \quad (71)$$

Integrating over Δm we find the density of jumps with overlap q as

$$\rho(q) = \sqrt{\frac{1 - q}{\pi}} \nu(q), \quad (72)$$

or for the density of flipped spins, $N_{\text{fl}} = \frac{(1 - q)N}{2}$

$$\mathcal{D}(N_{\text{fl}}) dN_{\text{fl}} = \frac{1}{\sqrt{\pi}} \frac{2}{N} \sqrt{\frac{2N_{\text{fl}}}{N}} \nu\left(q = 1 - \frac{2N_{\text{fl}}}{N}\right) dN_{\text{fl}}. \quad (73)$$

Let us now consider avalanches with $N_{\text{fl}} \ll N$. Using Eq. (60), we find

$$\rho(q) = \frac{C}{\sqrt{\pi}} \frac{1}{1 - q}, \quad (74)$$

and the power law density

$$\mathcal{D}(N_{\text{fl}}) = \frac{C}{\sqrt{\pi}} \frac{1}{N_{\text{fl}}^\rho}, \quad (75)$$

with $\rho = 1$.

D. Comparison with numerical work

For the SK model, there is no numerical study of equilibrium avalanches to date. However, in a pioneering

work, out-of-equilibrium avalanches at $T = 0$ were studied numerically along the hysteresis loop³¹, and found to exhibit criticality, i.e. a power-law distribution of magnetization jumps. The external field H is increased adiabatically slowly until a single spin becomes unstable. The latter is flipped and triggers with finite probability an avalanche of further spin flips, during which H is kept fixed. The typical difference in applied magnetic field between adjacent jumps scales as $N^{-1/2}$, which is the same scaling as in our calculation. During the avalanche a sequential single-spin-flip update was used to ensure the decrease of the total energy. Interestingly they observe the same scaling of the jumps of total magnetization, $\Delta M \sim N^{1/2}$, and the number of spin flips (which we assume to be of the same order as the number of spins that have flipped an odd number of times), $N_{\text{fl}} \sim N$, as in our present calculation for equilibrium. It is interesting to note that this implies that a typical spin flips on the order of $N^{1/2}$ times along one branch of the hysteresis loop. A very similar density of avalanches with the same exponents $\tau = \rho = 1$ and a crossover at $\Delta m \sim 1$, as analytically obtained for the statics here, was observed in the numerics. This similarity is surprising since the states reached along the hysteresis curve are quite far from the ground state, as evidenced by the width of the hysteresis loop. Nevertheless, the visited states share an important feature with the ground state: self-organized criticality. Indeed, the distribution of the local fields $h_i = \sum_{j \neq i} J_{ij} \sigma_j + H$, i.e., the energy cost to flip spin i only, is observed to display a linear pseudogap³¹ as in the equilibrium³², marginally satisfying the minimal requirement for metastability.

To understand better the relation between static and dynamic avalanches in the SK model, it would be useful to perform both equilibrium and dynamic simulations. In particular, it would be interesting to determine the prefactor of the power-law for the density of jumps, which we have computed here for equilibrium, but which has not been determined in Ref. 31, because they normalized the jump density. It would also be interesting to compute the probability density of overlaps between states before and after an avalanche, and compare with the expression (71) derived in equilibrium.

One could measure the joint density of overlaps and avalanche-sizes,

$$\rho_H(\Delta m, q) := \left\langle \delta\left(q - 1 + \frac{2N_{\text{fl}}}{N}\right) \delta\left(\Delta m - \frac{\Delta M}{\sqrt{N}}\right) \right\rangle_H, \quad (76)$$

where the average is taken for fixed external magnetic field (i.e., in practice for $H \in [H - \delta H, H + \delta H]$, with δH small). It would be interesting to check whether this joint density takes a form as in Eq. (71) with $\langle \Delta m^2 \rangle_q = 2(1 - q)$. In this case, this might allow to define a *dynamical* overlap-distribution $\nu(q)$ (to be interpreted as the $T = 0$ limit of $P_{\text{dyn}}(q)/T$).

V. DROPLET ARGUMENT IN ANY d

Let us now discuss the Edwards-Anderson model in dimension d . We first give a scaling argument to predict the avalanche exponent based on a droplet picture. Subsequently we will show how the previous result for the SK model can be recovered and interpreted in the same spirit.

To determine the first avalanche as the field is increased, we need information about the lowest-energy excitations of a given magnetization, which will scale inversely with the volume. More precisely, we expect the lowest excitation energy for a droplet-like excitation of linear size L to scale as

$$E_{\text{min}}(L) \sim \frac{1}{\nu_0} \frac{L^\theta}{V/L^{d_f}}. \quad (77)$$

This is argued as follows: Standard droplet arguments³⁰ stipulate that the lowest-energy excitation of linear size L , including a given spin, grows typically as L^θ . These droplets are in general objects of fractal dimension $d_f \leq d$. We thus assume that one can cover the system of volume V by V/L^{d_f} droplets, and that they are uncorrelated. This implies the scaling (77) for the droplet of minimal energy. The density ρ_0 of such single-droplet excitations near the ground state thus behaves as $\rho_0 dE = dE/E_{\text{min}}(L)$, or $\rho_0 = \nu_0/L^\theta \times V/L^{d_f}$.

The magnetization jump associated with the overturn of a droplet of size L is assumed to scale as L^{d_m} . Of course, $d_m \leq d_f$. The numerical study⁴⁶ suggests that d_m is rather close to d_f . We assume the total magnetization of droplets of size L to be uncorrelated with the energy, and distributed as $P_L(\Delta M) = L^{-d_m} \psi_M(\Delta M/L^{d_m})$. In a vanishing field, low-energy droplets are believed to exist at all length scales.

We make the standard assumption that droplets at scale L are uncorrelated from droplets at scales $\geq 2L$. By analogy with the reasoning given for the SK model, one argues that the density of avalanches per volume, per unit field H , and per unit magnetization change ΔM is given by

$$\rho(\Delta M) \approx \lim_{\delta H \downarrow 0} \frac{1}{V} \int_1^\infty \frac{dL}{L} \int_0^\infty \frac{dE}{E_{\text{min}}(L)} \times \delta\left(\delta H - \frac{E}{\Delta M}\right) P_L(\Delta M). \quad (78)$$

Using the above expressions one finds

$$\rho(\Delta M) \approx \frac{1}{(\Delta M)^\tau} \frac{\nu_0}{d_m} \int_0^\infty dz \psi_M(z) z^\tau, \quad (79)$$

valid for $\Delta M \gg 1$, with the avalanche exponent

$$\tau = \frac{d_f + \theta}{d_m}. \quad (80)$$

This prediction is very general. As discussed in Ref. 16, it also gives reasonable predictions for elastic interfaces in random media. The formula was recently rediscovered

in the context of the ferromagnetic phase of the random-field Ising model⁴⁹, in which case $d_m = d_f$, and thus $\tau = 1 + \theta/d_f$.⁴⁸

It is interesting to point out the close analogy between the exact expression for the SK model (57) and the heuristic droplet argument (78). In the SK model the role of spatial scale is played by the overlap distance $1 - q$, and the logarithmic sum over scales $\int dL/L$ goes over into an integral $dq/(1 - q)$. The equivalent of $E_{\min}(L)$ is given by the typical gap at distance $1 - q$, which is known to be⁴⁰ $\Delta_q = (1 - q)^{1/2}$. Finally, the distribution of magnetizations at fixed droplet scale, $P_L(\Delta M)$ is given by

$$P_L(\Delta M) = \frac{\exp\left(-\frac{(\Delta m)^2}{4(1-q)}\right)}{\sqrt{4\pi(1-q)}}.$$
 Putting these elements together and substituting them into Eq. (78) without the volume normalization factor, one recovers expression (70) with $\nu(q)$ given in (60). Note that changing variables from H to $h = N^{1/2}H$ and ΔM to $\Delta m = N^{-1/2}\Delta M$ does not change the density of avalanche sizes per unit field and unit jump size.

In the presence of a finite field H , droplets are believed to be suppressed above a scale $L_H \sim 1/H^\gamma$ (with $\gamma > 0$). This implies that integration over droplet scales in Eq. (78) is cut off at L_H leading to

$$\rho(\Delta M) = \frac{1}{(\Delta M)^\tau} \frac{\nu_0}{d_m} \int_{\Delta M/L_H^{d_m}}^{\infty} dz \psi_M(z) z^\tau, \quad (81)$$

which cuts off the power-law decay of the avalanche-size distribution at $\Delta M \sim L_H^{d_m}$.

At small but non-zero temperature we expect several effects. First, there is a thermal rounding of all the magnetization jumps, which is apparent in Eq. (48) and was discussed there. The equilibrium jumps are smeared out over an interval $\Delta h \sim T/\sqrt{T\chi_{\text{FC}}}$. In order to be distinguishable from the sample-averaged increase of magnetization, the avalanches should be bigger than the latter $\Delta m \gg \Delta h \chi_{\text{FC}} \sim \sqrt{T\chi_{\text{FC}}} \sim T$. Above this scale, the avalanche distribution is unchanged for $T \ll T_c$.

VI. CONCLUSION

We have introduced a method based on replica techniques to compute the cumulants of the equilibrium magnetization in the SK model at different fields. From their non-analytic part we have extracted the distribution of magnetization jumps at $T = 0$. It exhibits an interesting power-law behavior, characteristic of the criticality of the spin-glass phase. We have also obtained a prediction of the avalanche-size exponent for spin glasses in any dimension using droplet arguments. We have compared with numerical simulations of the out-of-equilibrium dy-

namics of the SK model and found striking similarities with the static calculations presented here.

It would be very interesting to investigate avalanches in small fields in realistic models, as the finite-range Edwards-Anderson model in 2 and 3 dimensions, to test some of the predictions that we obtained using droplet arguments. Furthermore, experimental measurements of power-law Barkhausen noise in spin glasses (e.g., by monitoring magnetization bursts^{8,44}) could provide complementary insight to earlier investigations of equilibrium noise⁴⁵.

We expect similar critical response upon slow changes of system parameters in many other systems described by continuous replica-symmetry breaking, as, e.g., in various optimization problems (minimal vertex cover²⁴, coloring²⁵, and k -satisfiability²⁶ close to the satisfiability threshold, and in the UNSAT region at large k). Likewise, in models of complex economic systems, one expects a power-law distributed market response to changes in prices and stocks²⁷. Avalanches have also been predicted to occur in electron glasses with unscreened $1/r$ interactions, and have been studied numerically in detail in Ref. 29. They find an avalanche exponent $\tau = 3/2$, which is reminiscent of the value found for disordered interfaces and random-field systems at the upper critical dimension.

Finally, we comment on possible future avenues to explore. It would be interesting to study analytically the dynamics of avalanches in the SK model. In principle one could use methods developed for the aging dynamics⁴¹. In the simplest framework, one studies relaxation from a random initial state, in which case the overlap between initial and final state vanishes at large time. Presumably the hysteresis cycle selects a sequence of states which have non-trivial subsequent overlaps. This remains a challenge to describe analytically. A more modest, but still non-trivial goal consists in describing the dynamics starting from an equilibrium state upon an increase of magnetic field by a small amount $\sim N^{-1/2}$.

It would be interesting to study whether the states visited dynamically along the hysteresis curve, and the avalanches triggered, have a relation with the marginal TAP states at high energies and their distinct soft modes⁵⁰. It would also be interesting to analyze the multi-shock terms $O(|h|^{k>1})$ in the magnetization cumulants, allowing to determine whether there are correlations between successive jumps.

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Appendix A: Zero'th order cumulant for the magnetization

Here we evaluate the contribution of ϕ^0 , Eq. (35). At $T = 0$, one can set $H[\vec{y}] \rightarrow \max_i \{y_i\}$, to simplify to

$$\begin{aligned}
\overline{m_{h_1} \dots m_{h_p}}^{J,c,(0)} &= -(-T)^p \int d^p y \delta\left(\sum_i \alpha_i y_i\right) \partial_{h_1} \dots \partial_{h_p} \overline{\max\{\vec{y} + z\vec{h}\sqrt{q(1)-q_m}\}}^z \\
&= (-T)^{p-1} \sqrt{q(1)-q_m} \int d^p y \delta\left(\sum_i \alpha_i y_i\right) \partial_{h_2} \dots \partial_{h_p} z \overline{\prod_{i=2}^p \Theta\left(y_1 - y_i + \beta z \sqrt{q(1)-q_m} [h_1 - h_i]\right)}^z \\
&= \sqrt{q(1)-q_m}^p \int d^p y \delta\left(\sum_i \alpha_i y_i\right) z^p \overline{\prod_{i=2}^p \delta\left(y_1 - y_i + \beta z \sqrt{q(1)-q_m} [h_1 - h_i]\right)}^z \\
&= \sqrt{q(1)-q_m}^p \int dy_1 \delta\left(y_1 + \sum_{i=2}^p \alpha_i \beta z \sqrt{q(1)-q_m} [h_1 - h_i]\right) z^p \\
&= [q(1)-q_m]^{p/2} \overline{z^p} = [2(q(1)-q_m)]^{p/2} \frac{[(-1)^p + 1] \Gamma\left(\frac{p+1}{2}\right)}{2\sqrt{\pi}}, \tag{A1}
\end{aligned}$$

which is the result given in the text.

Appendix B: Magnetization cumulants to first order in the shock expansion

Consider formula (46). In the limit of $T \rightarrow 0$, $\hat{h} = h/T$ becomes very large, and we can approximate $H(\vec{y}) = \max_i(y_i)$. The idea of the following calculation is that taking a field derivative yields a derivative of $H(\vec{y})$, which is a δ -function, eliminating one integration.

To evaluate (46), we start with the cross-term, and choose without loss of generality $\hat{h}_1 \leq \hat{h}_2 \leq \dots \leq \hat{h}_p$:

$$(-1)^p \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \frac{T}{2} \int_{q_m}^{q(u_c)} dq \frac{d\hat{u}(q)}{dq} \overline{\prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta\left(\sum_i \alpha_i y_i\right) H\left(\vec{y} + \vec{\hat{h}} A_M\right) H\left(\vec{y} + \vec{\hat{h}} A_m\right)}^{A_+, A_-}, \tag{B1}$$

where we have denoted $A_M := \max(A_+, A_-)$ and $A_m := \min(A_+, A_-)$. The derivatives can be written as

$$\partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \left[H\left(\vec{y} + \vec{\hat{h}} A_M\right) H\left(\vec{y} + \vec{\hat{h}} A_m\right) \right] = \sum_{m=0}^p \sum_{\{j_i\}, \{k_i\}} \partial_{\hat{h}_{j_1}} \dots \partial_{\hat{h}_{j_m}} H\left(\vec{y} + \vec{\hat{h}} A_M\right) \partial_{\hat{h}_{k_1}} \dots \partial_{\hat{h}_{k_{p-m}}} H\left(\vec{y} + \vec{\hat{h}} A_m\right), \tag{B2}$$

where the sum is over partitions of the p fields \hat{h}_i into two groups of m and $p-m$ fields with $j_1 < \dots < j_m$ and $k_1 < \dots < k_{p-m}$. The multiple derivative (with at least one derivative) of the first factor of H can be written as

$$\partial_{\hat{h}_{j_1}} \dots \partial_{\hat{h}_{j_m}} H\left(\vec{y} + \vec{\hat{h}} A_M\right) = (-1)^{m-1} A_M^m \prod_{\ell=2}^m \delta(y_{j_1} + \hat{h}_{j_1} A_M - y_{j_\ell} - \hat{h}_{j_\ell} A_M) \prod_{i=1}^{p-m} \Theta(y_{j_1} + \hat{h}_{j_1} A_M - y_{k_i} - \hat{h}_{k_i} A_m), \tag{B3}$$

This equation is proven by noting that

1. $\max(y_1, \dots, y_p) = \sum_{i=1}^p y_i \prod_{l \neq i} \theta(y_i - y_l)$.
2. $\partial_{y_i} \max(y_1, \dots, y_p) = \prod_{l \neq i} \theta(y_i - y_l)$, since derivatives of the θ -functions cancel in pairs.
3. a further derivative of $\theta(y_i - y_l)$ w.r.t. y_l gives $-\delta(y_i - y_l)$.

This result is a consequence of the fact that the maximum of m variables depends on $p \leq m$ variables if and only if these are mutually equal. We note that this expression is symmetric in the $\{\hat{h}_{j_1}, \dots, \hat{h}_{j_m}\}$, and that a similar expression holds for the second factor.

The terms $m = 0$ and $m = p$ have to be considered separately, which we do now, starting with $m = p$: Using (B3) and eliminating all the δ -functions from the derivatives of H yields

$$\begin{aligned} & \prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta \left(\sum_i \alpha_i y_i \right) \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} H(\vec{y} + \vec{\hat{h}} A_M) H(\vec{y} + \vec{\hat{h}} A_m) \\ &= (-1)^{p-1} A_M^p \int_{-\infty}^{\infty} dy_1 \delta \left(\sum_i \alpha_i [y_1 + \hat{h}_1 A_M - \hat{h}_i A_m] \right) \max_i \left\{ y_1 + \hat{h}_1 A_M - \hat{h}_i (A_M - A_m) \right\} \\ &= (-1)^{p-1} A_M^p \left(A_M \sum_i \alpha_i \hat{h}_i - \hat{h}_1 (A_M - A_m) \right), \end{aligned} \quad (\text{B4})$$

where to get to the last line we have used $\sum_i \alpha_i = 1$ and $\min_i \{\hat{h}_i\} = \hat{h}_1$.

Likewise the term $m = 0$ gives

$$\begin{aligned} & \prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta \left(\sum_i \alpha_i y_i \right) H(\vec{y} + \vec{\hat{h}} A_M) \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} H(\vec{y} + \vec{\hat{h}} A_m) \\ &= (-1)^{p-1} A_m^p \left(A_m \sum_i \alpha_i \hat{h}_i + \hat{h}_p (A_M - A_m) \right). \end{aligned} \quad (\text{B5})$$

Let us now discuss the terms $m = 1, \dots, p-1$. Consider

$$\begin{aligned} & \prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta \left(\sum_i \alpha_i y_i \right) \partial_{\hat{h}_{j_1}} \dots \partial_{\hat{h}_{j_m}} H(\vec{y} + \vec{\hat{h}} A_M) \partial_{\hat{h}_{k_1}} \dots \partial_{\hat{h}_{k_{p-m}}} H(\vec{y} + \vec{\hat{h}} A_m) \\ &= (-1)^{p-2} A_M^m A_m^{p-m} \int_{-\infty}^{\infty} dy_{j_1} \int_{-\infty}^{\infty} dy_{k_1} \prod_{i=1}^{p-m} \Theta(y_{j_1} + \hat{h}_{j_1} A_M - y_{k_i} - \hat{h}_{k_i} A_m - (A_M - A_m) \hat{h}_{k_i}) \\ & \quad \times \prod_{l=1}^m \Theta \left(- \left[y_{j_1} + \hat{h}_{j_1} A_M - y_{k_1} - \hat{h}_{k_1} A_m \right] + (A_M - A_m) \hat{h}_{j_\ell} \right) \\ & \quad \times \delta \left(\sum_{\ell} \alpha_{\ell} (y_{j_1} + A_M (\hat{h}_{j_1} - \hat{h}_{j_\ell}) + \sum_i \alpha_i (y_{k_i} + A_m (\hat{h}_{k_i} - \hat{h}_{k_i})) \right) \\ &= (-1)^{p-2} A_M^m A_m^{p-m} \int_{-\infty}^{\infty} dy_{j_1} \int_{-\infty}^{\infty} dy_{k_1} \Theta(y_{j_1} + \hat{h}_{j_1} A_M - y_{k_1} - \hat{h}_{k_1} A_m - (A_M - A_m) \max_{i=1, \dots, p-m} \hat{h}_{k_i}) \\ & \quad \times \Theta \left(- \left[y_{j_1} + \hat{h}_{j_1} A_M - y_{k_1} - \hat{h}_{k_1} A_m \right] + (A_M - A_m) \min_{\ell=1, \dots, m} \hat{h}_{j_\ell} \right) \\ & \quad \times \delta \left(\sum_{\ell} \alpha_{\ell} (y_{j_1} + A_M (\hat{h}_{j_1} - \hat{h}_{j_\ell}) + \sum_i \alpha_i (y_{k_i} + A_m (\hat{h}_{k_i} - \hat{h}_{k_i})) \right) \end{aligned} \quad (\text{B6})$$

Note that by going from the first to the second line, we have used the δ -functions to fix $y_{j_\ell} = y_{j_1} + (\hat{h}_{j_1} - \hat{h}_{j_\ell}) A_M$, and $y_{k_i} = y_{k_1} + (\hat{h}_{k_1} - \hat{h}_{k_i}) A_m$. From the second to the third line we have used that $A_M - A_m \geq 0$ to simplify the products of Θ -functions.

The product of the two Θ functions implies that the contribution is non-zero only if the partitions satisfy $\hat{h}_{j_\ell} > \hat{h}_{k_i}$ for all i, ℓ . Since we ordered $\hat{h}_1 \leq \dots \leq \hat{h}_p$, this identifies the set of \hat{h}_{k_i} to be $\{\hat{h}_1, \dots, \hat{h}_{p-m}\}$, and the set of \hat{h}_{j_ℓ} to be $\{\hat{h}_{p-m+1}, \dots, \hat{h}_p\}$.

Making in (B6) the shift of variables $y_{j_1} \rightarrow y_{j_1} + y_{k_1}$ eliminates y_{k_1} from the Θ functions, and allows to do the integral over the latter, resulting into

$$\begin{aligned} (\text{B6}) &= (-1)^{p-2} A_M^m A_m^{p-m} \int_{-\infty}^{\infty} dy_{j_1} \Theta(y_{j_1} + \hat{h}_{j_1} A_M - \hat{h}_{k_1} A_m - (A_M - A_m) \max_{i=1, \dots, p-m} \{\hat{h}_{k_i}\}) \\ & \quad \times \Theta \left(- \left[y_{j_1} + \hat{h}_{j_1} A_M - \hat{h}_{k_1} A_m \right] + (A_M - A_m) \min_{\ell=1, \dots, m} \{\hat{h}_{j_\ell}\} \right) \\ &= (-1)^{p-2} A_M^m A_m^{p-m} \int_{-\infty}^{\infty} dy_{j_1} \Theta(y_{j_1} - (A_M - A_m) \hat{h}_{p-m-1}) \Theta(-y_{j_1} + (A_M - A_m) \hat{h}_{p-m}) \\ &= (-1)^p A_M^m A_m^{p-m} (A_M - A_m) (\hat{h}_{p-m+1} - \hat{h}_{p-m}) \end{aligned} \quad (\text{B7})$$

Putting all terms together, (B1) becomes

$$\begin{aligned}
& (-1)^p \prod_{i=1}^p \int_{-\infty}^{\infty} dy_i \delta\left(\sum_i \alpha_i y_i\right) \partial_{\hat{h}_1} \dots \partial_{\hat{h}_p} \left[H\left(\vec{y} + \vec{\hat{h}} A_M\right) H\left(\vec{y} + \vec{\hat{h}} A_m\right) \right] \\
& = -(A_M^{p+1} + A_m^{p+1}) \bar{h} + (A_M - A_m) \left(-\hat{h}_p A_m^p + \sum_{m=1}^{p-1} (\hat{h}_{p-m+1} - \hat{h}_{p-m}) A_m^{p-m} A_M^m + \hat{h}_1 A_M^p \right). \quad (B8)
\end{aligned}$$

where $\bar{h} := \sum_i \alpha_i \hat{h}_i$. The first term $\sim \bar{h}$ disappears once we subtract the contributions from the non-crossed terms $\frac{1}{2} [H(\vec{y} + \vec{\hat{h}} A_M) H(\vec{y} + \vec{\hat{h}} A_m)]$ and $\frac{1}{2} [H(\vec{y} + \vec{\hat{h}} A_m) H(\vec{y} + \vec{\hat{h}} A_M)]$. This leads to the formula (50) given in the text.

Appendix C: Proof of Eq. (21)

Here we prove that for all sets of μ_a with replica indices $a = 1, \dots, n$ the identity

$$\sum'_{i_a \in \{1, \dots, p\} | \sum_a \delta_{j, i_a} = n \alpha_j} \exp\left(\sum_{a=1}^n h_{i_a} \mu_a\right) = \frac{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta\left(\sum_{i=1}^p \alpha_i y_i\right) \prod_{a=1}^n [\sum_{i=1}^p \exp(h_i \mu_a + y_i)]}{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta\left(\sum_{i=1}^p \alpha_i y_i\right) [\sum_{i=1}^p \exp(y_i)]^n}. \quad (C1)$$

holds. By definition of the primed sum, the left hand side reduces to 1 for $\mu_a = 0$, in which case the identity is trivial. We now prove the identity by series expansion in $\mu_a \neq 0$.

We define

$$K_i(\mu_a) := \frac{\exp(h_i \mu_a)}{\frac{1}{p} \sum_{j=1}^p \exp(h_j \mu_a)} - 1, \quad (C2)$$

which has the property that $K_i(\mu_a = 0) = 0$, as well as $\sum_{i=1}^p K_i(\mu_a) = 0$. We can then write

$$\exp(h_i \mu_a) = [1 + K_i(\mu_a)] \frac{1}{p} \sum_{j=1}^p \exp(h_j \mu_a). \quad (C3)$$

Analogously we define

$$\mathcal{N}(\vec{y}) := \frac{1}{p} \sum_{i=1}^p \exp(y_i), \quad (C4)$$

$$\Delta_i(\vec{y}) := \frac{\exp(y_i)}{\mathcal{N}(\vec{y})} - 1, \quad (C5)$$

so that $\sum_{i=1}^p \Delta_i(y) = 0$, and $\exp(y_i) = \mathcal{N}(\vec{y}) [1 + \Delta_i(\vec{y})]$. With this one finds

$$\begin{aligned}
& \sum_{i=1}^p e^{y_i} e^{\mu_a h_i} \\
& = \sum_{i=1}^p \mathcal{N}(\vec{y}) [1 + \Delta_i(\vec{y})] [1 + K_i(\mu_a)] \frac{1}{p} \sum_{j=1}^p \exp(h_j \mu_a) \\
& = \mathcal{N}(\vec{y}) \sum_{j=1}^p \exp(h_j \mu_a) \left[1 + \frac{1}{p} \sum_{i=1}^p \Delta_i(\vec{y}) K_i(\mu_a) \right] \\
& = \mathcal{N}(\vec{y}) \sum_{j=1}^p \exp(h_j \mu_a) \left[1 + \sum_{i=1}^{p-1} \frac{\Delta_i(\vec{y}) - \Delta_p(\vec{y})}{p} K_i(\mu_a) \right]. \quad (C6)
\end{aligned}$$

With this notation the identity (C1) to be proven can be restated as

$$\begin{aligned}
& \sum'_{i_a \in \{1, \dots, p\} | \sum_a \delta_{j, i_a} = n \alpha_j} \prod_{a=1}^n [1 + K_{i_a}(\mu_a)] \\
& = \frac{1}{N} \int \prod_{i=1}^p dy_i \delta\left(\sum_{i=1}^p \alpha_i y_i\right) [\mathcal{N}(\vec{y})]^n \\
& \quad \times \prod_{a=1}^n \left[1 + \sum_{i=1}^{p-1} K_i(\mu_a) \frac{\Delta_i(\vec{y}) - \Delta_p(\vec{y})}{p} \right], \quad (C7)
\end{aligned}$$

where we have divided by the common factor $\prod_{a=1}^n \left(\frac{1}{p} \sum_{j=1}^p \exp(h_j \mu_a) \right)$ on both sides. The normalization N is defined as

$$N := \int \prod_{i=1}^p dy_i \delta\left(\sum_{i=1}^p \alpha_i y_i\right) [\mathcal{N}(\vec{y})]^n. \quad (C8)$$

This identity holds if and only if the coefficients of linearly independent products of factors of $K_i(\mu_a)$ are identical on both sides. Since \sum' is normalized, the identity holds for $K_i(\mu_a) = 0$, i.e., $\mu_a = 0$. We now consider products over factors K_i with i ranging over $1 \leq i \leq p-1$, since $K_p = -\sum_{i=1}^{p-1} K_i$. Consider a product with k_i factors $K_i(\mu_a)$ (with all μ_a different). The coefficient on the left-hand side is obtained from combinatoric considerations: A factor of K_i either comes directly from a term $(1 + K_i)$ in (C7), or it results from a term $(1 + K_p)$, upon replacing $K_p = -\sum_{i=1}^{p-1} K_i$. There are $\binom{k_i}{r_i} = k_i! / r_i! (k_i - r_i)!$ different ways to have r_i factors of the latter origin (each contributing a factor (-1) to

the coefficient) and $k_i - r_i$ of the former. Then, k_i of the $(n\alpha_i)$ μ -indices with $i_a = i$ are already assigned, while the remaining $n\alpha_i - k_i$ indices i need still to be assigned to a subset of the $n - \sum_{i=1}^{p-1} k_i$ replica with yet unfixed i_a . The number of possibilities to make disjoint assignments for all indices $i = 1, \dots, p$ is

$$\frac{(n - \sum_{i=1}^{p-1} k_i)!}{(n\alpha_p - \sum_{i=1}^{p-1} r_i)! \prod_{i=1}^{p-1} (n\alpha_i - k_i + r_i)!}. \quad (C9)$$

This is normalized by the number of assignments of $n\alpha_i$

indices i to unconstrained replica a ,

$$\frac{n!}{\prod_{i=1}^p (n\alpha_i)!}. \quad (C10)$$

Putting all elements together, the sought coefficient follows as

$$C_{\{k_i\}} \equiv \sum_{r_1=0}^{k_1} \dots \sum_{r_{p-1}=0}^{k_{p-1}} \frac{(n - \sum_{i=1}^{p-1} k_i)!}{(n\alpha_p - \sum_{i=1}^{p-1} r_i)! \prod_{i=1}^{p-1} (n\alpha_i - k_i + r_i)!} \times \frac{\prod_{i=1}^p (n\alpha_i)!}{n!} \prod_{i=1}^{p-1} (-1)^{r_i} \binom{k_i}{r_i}. \quad (C11)$$

On the other hand, the coefficient on the right-hand side is given by

$$\begin{aligned} C'_{\{k_i\}} &= \frac{1}{N} \int \prod_{i=1}^p dy_i \delta \left(\sum_{i=1}^p \alpha_i y_i \right) \prod_{i=1}^{p-1} \left[\frac{\Delta_i(\vec{y}) - \Delta_p(\vec{y})}{p} \right]^{k_i} [\mathcal{N}(\vec{y})]^n \\ &= \frac{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta(\sum_{i=1}^p \alpha_i y_i) \prod_{i=1}^{p-1} (e^{y_i} - e^{y_p})^{k_i} (\sum_{i=1}^p e^{y_i})^{n - \sum_{i=1}^{p-1} k_i}}{\int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta(\sum_{i=1}^p \alpha_i y_i) (\sum_{i=1}^p e^{y_i})^n}. \end{aligned} \quad (C12)$$

Our task is to show that $C_{\{k_i\}} = C'_{\{k_i\}}$. We note that a priori $C_{\{k_i\}}$ is only defined for integer and positive $n\alpha_i$, while $C'_{\{k_i\}}$ is only defined for $n < 0$, but not necessarily integer. We will show that $C'_{\{k_i\}}$ has an analytic continuation to positive n and $n\alpha_i$ which indeed coincides with $C_{\{k_i\}}$ where the latter is defined. Thus we interpret $C'_{\{k_i\}}$ as the analytical continuation of the replica expression, which can then be continued to $n \uparrow 0$.

Let us proceed by computing the numerator in Eq. (C12) (recalling that everywhere we assume $\sum_{i=1}^p \alpha_i = 1$)

$$\begin{aligned} B_{\{k_i\}} &:= \int_{-\infty}^{\infty} \prod_{i=1}^p dy_i \delta \left(\sum_{i=1}^p \alpha_i y_i \right) \prod_{i=1}^{p-1} (e^{y_i} - e^{y_p})^{k_i} \left(\sum_{i=1}^p e^{y_i} \right)^{n - \sum_{i=1}^{p-1} k_i} \\ &= \int_{-\infty}^{\infty} \prod_{i=1}^{p-1} dy'_i dy_p \delta \left(\sum_{i=1}^{p-1} \alpha_i y'_i + y_p \right) e^{ny_p} \prod_{i=1}^{p-1} (e^{y'_i} - 1)^{k_i} \left(1 + \sum_{i=1}^{p-1} e^{y'_i} \right)^{n - \sum_{i=1}^{p-1} k_i} \\ &= \int_{-\infty}^{\infty} \prod_{i=1}^{p-1} dy'_i \prod_{i=1}^{p-1} \left[e^{-n\alpha_i y'_i} (e^{y'_i} - 1)^{k_i} \right] \left(1 + \sum_{i=1}^{p-1} e^{y'_i} \right)^{n - \sum_{i=1}^{p-1} k_i} \\ &= \frac{1}{\Gamma(-n + \sum_{i=1}^{p-1} k_i)} \int_0^{\infty} \frac{d\lambda}{\lambda^{1+n - \sum_{i=1}^{p-1} k_i}} \int_{-\infty}^{\infty} \prod_{i=1}^{p-1} dy'_i e^{-\lambda(1 + \sum_{i=1}^{p-1} e^{y'_i})} \prod_{i=1}^{p-1} \left[e^{-n\alpha_i y'_i} (e^{y'_i} - 1)^{k_i} \right]. \end{aligned} \quad (C13)$$

Now we change variables to $a_i = e^{y'_i}$ and expand the powers,

$$\begin{aligned} B_{\{k_i\}} &= \frac{1}{\Gamma(-n + \sum_{i=1}^{p-1} k_i)} \int_0^{\infty} \frac{d\lambda e^{-\lambda}}{\lambda^{1+n - \sum_{i=1}^{p-1} k_i}} \prod_{i=1}^{p-1} \int_0^{\infty} da_i \sum_{r_i=0}^{k_i} \binom{k_i}{r_i} (-1)^{r_i} a_i^{k_i - r_i - n\alpha_i - 1} e^{-\lambda a_i} \\ &= \frac{1}{\Gamma(-n + \sum_{i=1}^{p-1} k_i)} \int_0^{\infty} \frac{d\lambda e^{-\lambda}}{\lambda^{1+n - \sum_{i=1}^{p-1} k_i}} \prod_{i=1}^{p-1} \sum_{r_i=0}^{k_i} \binom{k_i}{r_i} (-1)^{r_i} \frac{\Gamma(k_i - r_i - n\alpha_i)}{\lambda^{k_i - r_i - n\alpha_i}} \\ &= \sum_{r_1=0}^{k_1} \dots \sum_{r_{p-1}=0}^{k_{p-1}} \frac{\Gamma(-n\alpha_p + \sum_{i=1}^{p-1} r_i)}{\Gamma(-n + \sum_{i=1}^{p-1} k_i)} \prod_{i=1}^{p-1} \binom{k_i}{r_i} (-1)^{r_i} \Gamma(k_i - r_i - n\alpha_i) \end{aligned} \quad (C14)$$

Finally, we use the relation $\Gamma(x) = \frac{\pi}{\sin(\pi x) \Gamma(1-x)}$ to rewrite this (using that k_i and r_i are integers) as

$$B_{\{k_i\}} = \frac{(-1)^{p-1} \sin(n\pi)/\pi}{\prod_{i=1}^p \sin(n\alpha_i \pi)/\pi} \sum_{\{0 \leq r_i \leq k_i\}} \frac{\Gamma(1 + n - \sum_{i=1}^{p-1} k_i)}{\Gamma(1 + n\alpha_p - \sum_{i=1}^{p-1} r_i) \prod_{i=1}^{p-1} \Gamma(1 + n\alpha_i - k_i + r_i)} \prod_{i=1}^{p-1} \binom{k_i}{r_i} (-1)^{r_i}. \quad (C15)$$

The ratio of Γ functions in Eq. (C15) can be continued to positive n . When n and all $n\alpha_i$ become integers, the latter can be written as

$$\frac{(n - \sum_{i=1}^{p-1} k_i)!}{(n\alpha_p - \sum_{i=1}^{p-1} r_i)! \prod_{i=1}^{p-1} (n\alpha_i - k_i + r_i)!}. \quad (\text{C16})$$

Dividing by the normalization factor yields indeed $C_{\{k_i\}}$, which completes the proof.

Note that the normalization factor in the denominator of Eq. (C12), for $n \rightarrow 0$ is given by

$$N(n \rightarrow 0) = \frac{(-1)^{p-1} \sin(n\pi)/\pi}{\prod_{i=1}^p \sin(n\alpha_i\pi)/\pi} [1 + O(n)], \quad (\text{C17})$$

which tends to $N \rightarrow 1/[(-n)^{p-1} \prod_i \alpha_i]$ when $n \uparrow 0$, as calculated previously in Eq. (26).

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$$P_d(L, E) dL dE = \frac{dL dE}{L L^\theta}. \quad (\text{C18})$$
 - In the main text we focus instead on the density per unit volume and energy, $\sigma = V^{-1} dE/E_{\min}(L) dL/L$, of droplet excitations of energy $E = \mathcal{O}(1)$ and size L . Since the probability that a given spin belongs to such a droplet is $L^{d_f} \sigma$, it follows that $\sigma = L^{-d_f} P_d(L, E)$.
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